

Mathematical and numerical analysis for multiscale simulations of suspensions

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including mathematical works with and by E. Cancès, I. Catto, Y. Gati,

numerical works with A.T. Patera (MIT) and S. Boyaval,

in collaboration with Ph. Coussot (LCPC), F. Lequeux (ESPCI).



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Modelling of suspensions

- The Hébraud-Lequeux model

A mesoscale model describing shear flows of concentrated suspensions

- A multiscale model based on the HL model

- Long-time existence and uniqueness
- Long-time limit (convergence to steady states)
- Numerical simulation (deterministic and stochastic approaches)

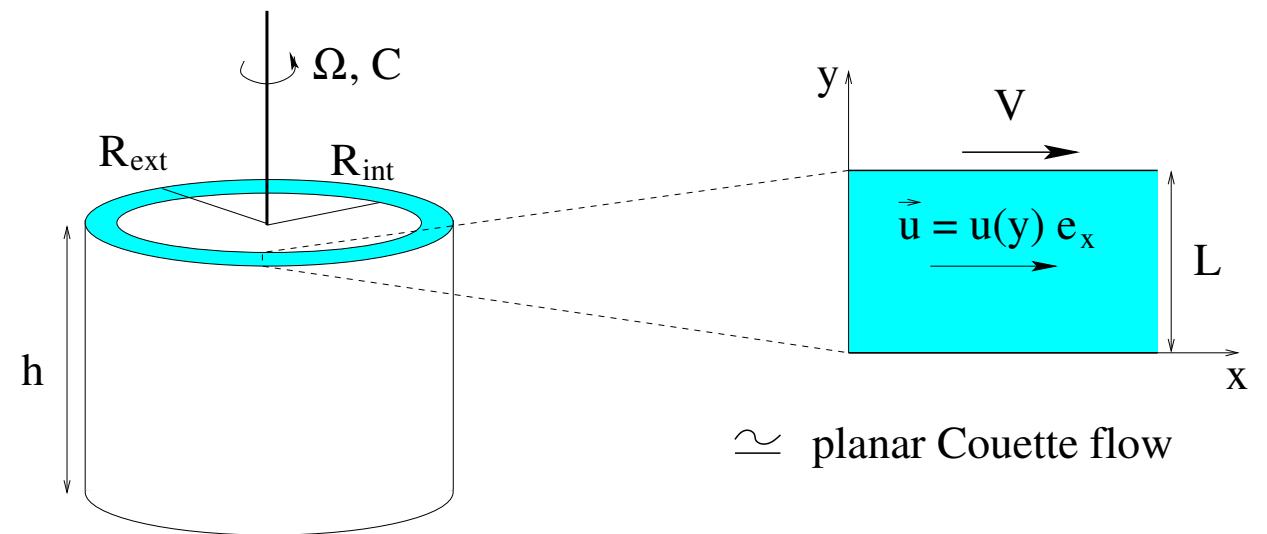


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Modelling of suspensions

Shear-stress experiments



\simeq planar Couette flow

$$\begin{pmatrix} \Omega \\ C \end{pmatrix}$$

\leftrightarrow

$$\begin{pmatrix} \dot{\gamma} \\ \tau \end{pmatrix}$$

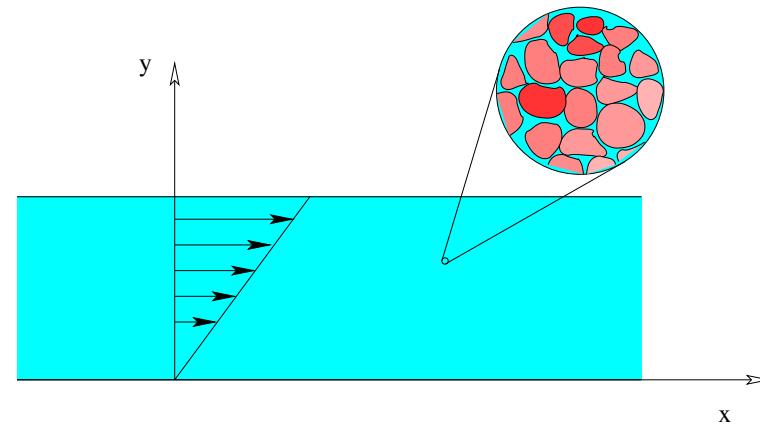
$$\dot{\gamma} = \frac{V}{L} = \frac{R_{\text{int}} \Omega}{R_{\text{ext}} - R_{\text{int}}}$$

$$\tau = \frac{C}{2\pi R_{\text{int}}^2 h}$$

Modelling of suspensions

Phys. Rev. Lett. 1998

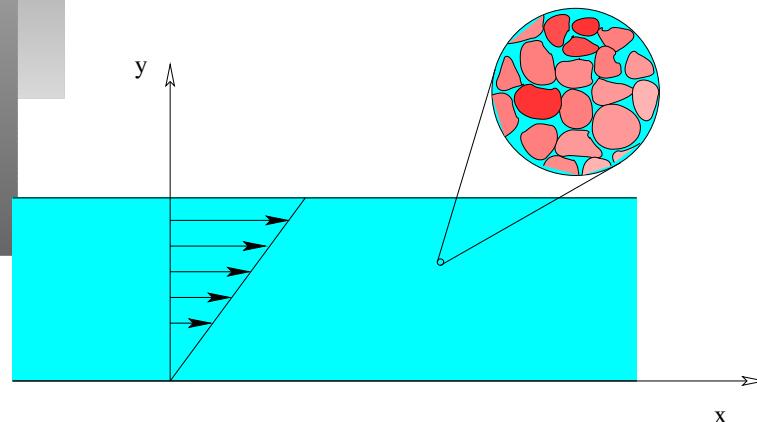
- Planar Couette flow: $\vec{u}(x, y, t) = u(y, t) \vec{e}_x$
- Shear rate $\dot{\gamma} = \partial_y u$ uniform in space



- A sample of matter: assembly of blocks, each of them carrying some shear stress σ .

Modelling of suspensions

The probability density $p(t, \sigma)$ for a block carry shear-stress σ at time t is independent of x and y .



Macroscopic shear stress in the fluid

$$\tau(t) = \int_{\mathbf{R}} \sigma p(\sigma, t) d\sigma$$

Modelling of suspensions

- Elasticity of individual blocks (shear modulus G_0)
- Relaxation beyond a given threshold σ_c
(T_0 : characteristic relaxation time)
- Collective effect: relaxation induced rearrangement

$$\begin{aligned}\partial_t p(t, \sigma) = & -G_0 \dot{\gamma}(t) \partial_\sigma p(t, \sigma) + D(p(t)) \partial_{\sigma\sigma}^2 p(t, \sigma) \\ & - \frac{\chi_{\mathbf{R} \setminus [-\sigma_c, \sigma_c]}(\sigma)}{T_0} p(t, \sigma) + \frac{1}{T_0} \left(\int_{|\sigma| > \sigma_c} p(t, \sigma) d\sigma \right) \delta_0(\sigma)\end{aligned}$$

with

$$D(f) = \frac{\alpha}{T_0} \int_{|\sigma| > \sigma_c} f(\sigma) d\sigma$$



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Modelling of suspensions

Hébraud-Lequeux (HL) equation

$$\begin{aligned}\partial_t p(t, \sigma) &= -G_0 \dot{\gamma}(t) \partial_\sigma p(t, \sigma) + D(p(t)) \partial_{\sigma\sigma} p(t, \sigma) \\ &\quad - \frac{\chi_{\mathbf{R} \setminus [-\sigma_c, \sigma_c]}(\sigma)}{T_0} p(t, \sigma) + \frac{D(p(t))}{\alpha} \delta_0(\sigma)\end{aligned}$$

$$D(f) = \frac{\alpha}{T_0} \int_{|\sigma| > \sigma_c} f(\sigma) d\sigma$$

Nonlinear (nonlocal) parabolic equation, which can degenerate into a linear advection equation

Nonlinear drift-diffusion process (in the sense of Mc-Kean) with jumps.



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Mesoscopic equation: steady-state

$\dot{\gamma}$ being given, search the solutions $p(\sigma)$ to

$$-G_0 \dot{\gamma} \partial_\sigma p + D(p) \partial_{\sigma\sigma} p - \frac{\chi_{\mathbf{R} \setminus [-\sigma_c, \sigma_c]}(\sigma)}{T_0} p + \frac{D(p)}{\alpha} \delta_0(\sigma) = 0$$

with

$$D(p) = \frac{\alpha}{T_0} \int_{|\sigma| > \sigma_c} p(\sigma) d\sigma$$

such that

$$p \geq 0, \quad \int_{\mathbf{R}} p(\sigma) d\sigma = 1$$



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Mesoscopic equation: steady-state

Proposition (E. Cancès, I. Catto, Y. Gati). For a given set of parameters α , G_0 , T_0 , and σ_c ,

- For $\dot{\gamma} \neq 0$ fixed, there exists a unique steady state $p(\sigma)$, and therefore a unique τ
- For $\dot{\gamma} = 0$, any function $p(\sigma)$ supported in $[-\sigma_c, \sigma_c]$ is a steady-state.

In addition, if $\alpha > \alpha_c = 1/2$, there exists a unique steady state $p(\sigma)$ with $D(p) > 0$.

No such state exists for $\alpha \leq \alpha_c$.



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Mesoscopic equation

$\dot{\gamma}(t)$ and p_0 such that $p_0 \geq 0$ and $\int_{\mathbf{R}} p_0 = 1$ being given, search the solutions $p(t, \sigma)$ to the HL equation

$$\begin{aligned}\partial_t p(t, \sigma) &= -G_0 \dot{\gamma}(t) \partial_\sigma p(t, \sigma) + D(p(t)) \partial_{\sigma\sigma} p(t, \sigma) \\ &\quad - \frac{\chi_{\mathbf{R} \setminus [-\sigma_c, \sigma_c]}(\sigma)}{T_0} p(t, \sigma) + \frac{D(p(t))}{\alpha} \delta_0(\sigma)\end{aligned}$$

with $p(0, \sigma) = p_0(\sigma)$.

$$D(f) = \frac{\alpha}{T_0} \int_{|\sigma| > \sigma_c} f(\sigma) d\sigma$$



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Mesoscopic equation

A priori estimates ($G_0 = 1, T_0 = 1, \sigma_c = 1$)

$$\int_{\mathbf{R}} (\text{HL equation})$$

$$\frac{d}{dt} \int_{\mathbf{R}} p = 0$$

$$\int_{\mathbf{R}} (\text{HL equation}) \times p$$

$$\frac{1}{2} \frac{d}{dt} \int_{\mathbf{R}} p^2 + D(p(t)) \int_{\mathbf{R}} |\partial_\sigma p|^2 + \int_{|\sigma| > 1} p^2 = \frac{D(p(t))}{\alpha} p(t, 0)$$



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Mesoscopic equation

Maximum principle

$$H_1 = \chi_{\mathbf{R} \setminus [-1,1]}$$

$$\begin{cases} \partial_t p = -\dot{\gamma} \partial_\sigma p + D(p) \partial_{\sigma\sigma} p - H_1 p + \frac{D(p)}{\alpha} \delta_0 ; \\ p(0, \sigma) = p_0(\sigma) , \end{cases}$$

$$\begin{cases} \partial_t p_- = -\dot{\gamma} \partial_\sigma p_- + D(p) \partial_{\sigma\sigma} p_- - p_- ; \\ p_-(0, \sigma) = p_0(\sigma) , \end{cases}$$

$$\begin{cases} \partial_t p_+ = -\dot{\gamma} \partial_\sigma p_+ + D(p) \partial_{\sigma\sigma} p_+ + \frac{D(p)}{\alpha} \delta_0(\sigma) ; \\ p_+(0, \sigma) = p_0(\sigma) , \end{cases}$$

$$p_- \leq p \leq p_+$$



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Mesoscopic equation

Heat kernel

$$\begin{cases} \mathcal{G}_t(\sigma) &= \frac{1}{\sqrt{4\pi t}} \exp\left(-\frac{\sigma^2}{4t}\right) \quad \text{if } t > 0 ; \\ \mathcal{G}_0 &= \delta_0 . \end{cases}$$

Total shear

$$\chi(t) = \int_0^t \dot{\gamma}(s) \, ds \quad \left[\in H_{\text{loc}, t}^1 \hookrightarrow C_t^0 \right]$$

$$p_- = e^{-t} \tau_{\chi(t)} p_0 \star \mathcal{G}_{\int_0^t D(p)} \\ p_+ = \tau_{\chi(t)} p_0 \star \mathcal{G}_{\int_0^t D(p)} + \frac{1}{\alpha} \int_0^t D(p(s)) \mathcal{G}_{\int_s^t D(p)} (\cdot - \chi(t) + \chi(s)) \, ds$$



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Mesoscopic equation

$$\begin{aligned} p(t, \sigma) &\leq p_+(t, \sigma) \\ &\leq \|\tau_{\chi(t)} p_0 \star \mathcal{G}_{\int_0^t D(p)}\|_{L^\infty} + \frac{1}{\alpha} \int_0^t \frac{D(p(s))}{\sqrt{4\pi \int_s^t D(p)}} ds \\ &\leq \|p_0\|_{L^\infty} + \frac{1}{\alpha\sqrt{\pi}} \sqrt{\int_0^t D(p)} \end{aligned}$$

$$D(p) = \alpha \int_{|\sigma| > \sigma_c} p \leq \alpha \int_{\mathbf{R}} p = \alpha$$

Therefore

$$0 \leq p(t, \sigma) \leq \|p_0\|_{L^\infty} + \sqrt{\frac{t}{\alpha\pi}}$$



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Mesoscopic equation

The subsolution p_- is used to prove that, if $D(p_0) > 0$, then $D(p(t))$ is bounded away from zero on finite time intervals.

As $D(p_0) > 0$, p_0 is not supported in $[-1, 1]$.

As $t \mapsto \chi(t)$ is continuous, $p_-(t) = e^{-t} \tau_{\chi(t)} p_0 \star \mathcal{G}_{\int_0^t D(p)}$ is not supported in $[-1, 1]$ for any $0 \leq t < t^*$.

In fact, for any $T < t^*$,

$$\forall 0 \leq t \leq T, \quad D(p(t)) \geq D(p_-(t)) \geq \frac{\alpha}{2} e^{-T} \min_{0 \leq t \leq T} \int_{|\sigma + \chi(t)| > 1} p_0$$



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Mesoscopic equation

As $\int_0^{t^*} D(p(t)) dt = \mathcal{D} > 0$, the support of

$$p_-(t^*) = e^{-t^*} \tau_{\chi(t^*)} p_0 \star \mathcal{G}_{\mathcal{D}}$$

is the whole real line.

Therefore, so is the support of

$$p_-(t) = e^{-(t-t^*)} \tau_{\chi(t-t^*)} p_-(t^*) \star \mathcal{G}_{\int_{t^*}^t D(p)}$$

for any $t \geq t^*$, and $D(p(t)) > 0$ for any t .



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Mesoscopic equation

Theorem (E. Cancès, I. Catto, Y. Gati). Let $\dot{\gamma} \in L^2_{\text{loc}}(\mathbf{R}_+)$ and let the initial data p_0 satisfy the conditions

$$p_0 \in L^1 \cap L^\infty(\mathbf{R}), \quad p_0 \geq 0, \quad \int_{\mathbf{R}} p_0 = 1, \quad \int_{\mathbf{R}} |\sigma| p_0 < +\infty$$

and be such that $D(p_0) > 0$.

Then, there exists a unique global solution $p(t, \sigma)$ to the HL equation in $L^\infty_{\text{loc}, t}(L_\sigma^1 \cap L_\sigma^2) \cap L^2_{\text{loc}, t}(H_\sigma^1)$.

Moreover, $p \in L^\infty_{\text{loc}, t}(L_\sigma^\infty) \cap C_t^0(L_\sigma^1 \cap L_\sigma^2)$

SIAM Journal on Mathematical Analysis, 37, pp 60-82, 2005,



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Mesoscopic equation

In addition,

- For all $t \geq 0$, $p(t, \cdot) \geq 0$, $\int_{\mathbf{R}} p(t, \sigma) d\sigma = 1$
- $D(p) \in C_t^0$ and for all $T > 0$

$$\min_{0 \leq t \leq T} D(p(t)) > 0$$

- $\sigma p \in L_t^\infty(L_\sigma^1)$ so that the macroscopic shear-stress

$$\tau(t) = \int_{\mathbf{R}} \sigma p(t, \sigma) d\sigma$$

is well-defined in $L_{loc, t}^\infty$



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Mesoscopic equation

Sketch of the proof

- Step 1. For any $0 < \epsilon \leq 1$, equation

$$\begin{cases} \partial_t p_\epsilon = -\dot{\gamma} \partial_\sigma p_\epsilon + (D(p_\epsilon) + \epsilon) \partial_{\sigma\sigma} p_\epsilon - H_1 p_\epsilon + \frac{D(p_\epsilon)}{\alpha} \delta_0 ; \\ p_\epsilon(0, \sigma) = p_0(\sigma) , \end{cases}$$

has a solution p_ϵ (a priori bounds + Schauder for local existence, growth control on $\int_{\mathbf{R}} |\sigma| p_\epsilon$ for global existence).

- Step 2. Up to extraction (p_ϵ) converges toward a solution of the HL equation when ϵ goes to zero.



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Mesoscopic equation

- Step 3. Uniqueness: let p_1 and p_2 be two solutions of the HL equations. Let $q = p_2 - p_1$.

Maximum principle: $p \geq p_- \Rightarrow \forall T > 0, \exists \nu(T) > 0$ depending only on α and p_0 such that

$$\min_{0 \leq t \leq T} D(p(t)) \geq \nu(T).$$

$$\frac{1}{2} \frac{d}{dt} \|q\|_{L_\sigma^2}^2 \leq \left(\frac{1}{\nu(T)} + \frac{\alpha^2}{\nu(T)} \|\partial_\sigma p_1\|_{L_\sigma^2}^2 + \frac{\nu(T)}{2} \right) \|q\|_{L_\sigma^2}^2$$

$$\text{Gronwall} \Rightarrow q = 0$$



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Mesoscopic equation

Proposition (E. Cancès, I. Catto, Y. Gati). Let the initial data p_0 satisfy the conditions

$$p_0 \in L^1 \cap L^\infty(\mathbf{R}), \quad p_0 \geq 0, \quad \int_{\mathbf{R}} p_0 = 1, \quad \int_{\mathbf{R}} |\sigma| p_0 < +\infty$$

and be such that

$$D(p_0) = 0.$$

Then, the HL equation has at least one solution, but may have an infinity of solutions.



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Mesoscopic equation: long-time behaviour

Theorem (E. Cancès and CLB). For α large enough, for $\dot{\gamma}_\infty$ small enough, for \mathcal{C} small enough, if

$$|\dot{\gamma}(t) - \dot{\gamma}_\infty| \leq \mathcal{C} f(t) \quad \text{with} \quad |f(t)| \leq 1 \quad \text{and} \quad f(t) \xrightarrow[t \rightarrow +\infty]{} 0,$$

and if p_0 is close enough to p_∞ [unique steady state associated with $\dot{\gamma}_\infty$ for which $D(p_\infty) > 0$], then

$$p(t, \cdot) \xrightarrow[t \rightarrow +\infty]{} p_\infty \quad \text{at least in } L^2_{loc}(\mathbf{R}) \cap L^1(\mathbf{R}).$$

If moreover, $\dot{\gamma}(t)$ converges exponentially fast to $\dot{\gamma}_\infty$, then $p(t, \cdot)$ converges exponentially fast to p_∞ .



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Mesoscopic equation: long-time behaviour

The proof makes use of the **entropy function**

$$S_2(t) = \int_{\mathbf{R}} \left(\frac{p(t, \sigma)}{p_\infty(\sigma)} - 1 \right)^2 p_\infty(\sigma) d\sigma$$

The assumption “ p_0 close enough to p_∞ ” means

$$S_2(0) = \int_{\mathbf{R}} \left(\frac{p_0(\sigma)}{p_\infty(\sigma)} - 1 \right)^2 p_\infty(\sigma) d\sigma$$

small enough.



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Multiscale model

It is observed in experiments that the shear rate $\partial_y u$ is not uniform in space. We therefore propose the following multiscale model:

$$\left\{ \begin{array}{lcl} \rho \partial_t u(t, y) & = & \mu \partial_{yy} u(t, y) + \partial_y \tau(t, y), \\ & & u(t, 0) = 0, \quad u(t, L) = V(t), \\ \\ \partial_t p(t, y, \sigma) & = & -G_0 \partial_y u(t, y) \partial_\sigma p(t, y, \sigma) + D(t, y) \partial_{\sigma\sigma}^2 p(t, y, \sigma) \\ & & - \frac{\chi_{\mathbf{R} \setminus [-\sigma_c, \sigma_c]}(\sigma)}{T_0} p(t, y, \sigma) + \frac{1}{T_0} \left(\int_{|\sigma'| > \sigma_c} p(t, y, \sigma') d\sigma' \right) \delta_0(\sigma) \\ \\ \tau(t, y) & = & \int_{\mathbf{R}} \sigma p(t, y, \sigma) d\sigma, \\ \\ D(t, y) & = & \frac{\alpha}{T_0} \int_{|\sigma| > \sigma_c} p(t, y, \sigma) d\sigma. \end{array} \right.$$



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$\rho > 0,$

 $\mu > 0$
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Multiscale model

Theorem (E. Cancès, I. Catto, Y. Gati and CLB). Let the initial data p_0 satisfy the conditions

$$\begin{cases} p_0 \geq 0, & \int_{\mathbf{R}} p_0(y, \sigma) d\sigma = 1, \quad \forall y \in \Omega =]0, L[, \\ p_0 \in L^\infty(\Omega \times \mathbf{R}), & \int_{\mathbf{R}} |\sigma| p_0 d\sigma \in L^2(\Omega); \end{cases}$$

together with

$$\inf_{y \in \Omega, \chi \in \mathbf{R}} \int_{|\sigma + \chi| > \sigma_c} p_0(y, \sigma) d\sigma = \eta > 0.$$

Let $V \in H_{\text{loc}, t}^1$ and $u_0 \in H^1(0, L)$ such that $u_0(0) = 0$ and $u_0(L) = V(0)$.



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Multiscale model

Then, there exists a unique global solution $(u; p)$ of the multiscale HL system such that

$$u \in C_t^0(L_y^2) \cap L_{\text{loc}, t}^2 H_y^1,$$

$$p \in L_{\text{loc}, t}^\infty(L_y^\infty(L_\sigma^1) \cap L_{y,\sigma}^\infty) \cap L_y^\infty(C_t^0(L_\sigma^2) \cap L_{\text{loc}, t}^2 H_\sigma^1)$$

and

$$\tau \in L_y^2(L_{\text{loc}, t}^\infty) \cap C_t^0(L_y^2).$$

Moreover,

$$p \geq 0 \quad \text{and} \quad \int_{\mathbf{R}} p(t, y, \sigma) d\sigma = 1, \quad \forall (t, y)$$

[SIAM Multiscale Modeling and Simulation, vol. 4, No. 4, pp 1041-1058, 2005,](#)



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Multiscale model

- Step 1. Change of variable $v(t, y) = u(t, y) - \frac{V(t)}{L}y$

$$\rho \partial_t v(t, y) = \mu \partial_{yy} v(t, y) + \partial_y \tau(t, y) - \frac{V'(t)}{L} y,$$

$$v(t, 0) = 0, \quad v(t, L) = 0,$$

$$\left\{ \begin{array}{l} \partial_t p(t, y, \sigma) = -G_0 \left(\partial_y v(t, y) + \frac{V(t)}{L} \right) \partial_\sigma p(t, y, \sigma) + D(t, y) \partial_{\sigma\sigma}^2 p(t, y, \sigma) \\ \qquad - \frac{\chi_{\mathbf{R} \setminus [-\sigma_c, \sigma_c]}(\sigma)}{T_0} p(t, y, \sigma) + \frac{1}{T_0} \left(\int_{|\sigma'| > \sigma_c} p(t, y, \sigma') d\sigma' \right) \delta_0(\sigma) \\ \tau(t, y) = \int_{\mathbf{R}} \sigma p(t, y, \sigma) d\sigma, \end{array} \right.$$

$$D(t, y) = \frac{\alpha}{T_0} \int_{|\sigma| > \sigma_c} p(t, y, \sigma) d\sigma.$$



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- Step 2. Short time existence and uniqueness

For $T > 0$ we define the mappings

$$\begin{aligned}\mathcal{F}_1 : \quad L^2(0, T; H_0^1(\Omega)) \quad &\longrightarrow \quad L^\infty(0, T; L^2(\Omega)) \\ v \qquad \qquad \qquad &\longmapsto \qquad \qquad \tau\end{aligned}$$

and

$$\begin{aligned}\mathcal{F}_2 : \quad L^\infty(0, T; L^2(\Omega)) \quad &\longrightarrow \quad L^2(0, T; H_0^1(\Omega)) \\ \tau \qquad \qquad \qquad &\longmapsto \qquad \qquad v ,\end{aligned}$$

For $T > 0$ small enough, $\mathcal{F} = \mathcal{F}_2 \circ \mathcal{F}_1$ is contractive.



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- Step 3. Global and time existence and uniqueness

Let $[0, t^*]$ be the maximal time interval on which the solution $(u; p)$ is defined.

For all $0 \leq t < t^*$,

- $\left\| \int_{\mathbf{R}} |\sigma| p(t) d\sigma \right\|_{L_y^2} \leq \left\| \int_{\mathbf{R}} |\sigma| p_0 d\sigma \right\|_{L_y^2} + C_{p_0} (1 + t^{3/2})$
- $\inf_{y \in \Omega, \chi \in \mathbf{R}} \int_{|\sigma + \chi| > \sigma_c} p(t, y, \sigma) d\sigma \geq \frac{\eta}{2\alpha} e^{-t}$



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Multiscale model: long-time behaviour

$$\left\{ \begin{array}{l} \rho \partial_t u = \mu \partial_{yy} u(y, t) + \partial_y \tau(y, t), \quad u(t, 0) = 0, \quad u(t, L) = V(t), \\ \\ \partial_t p(y, \sigma, t) = -G_0 \partial_y u(y, t) \partial_\sigma p(y, \sigma, t) + D(y, t) \partial_{\sigma\sigma}^2 p(y, \sigma, t) \\ \qquad - \frac{\chi_{\mathbf{R} \setminus [-\sigma_c, \sigma_c]}(\sigma)}{T_0} p(y, \sigma, t) + \frac{1}{T_0} \left(\int_{|\sigma'| > \sigma_c} p(y, \sigma', t) d\sigma' \right) \delta_0(\sigma) \\ \\ \tau(y, t) = \int_{\mathbf{R}} \sigma p(y, \sigma, t) d\sigma, \\ \\ D(y, t) = \frac{\alpha}{T_0} \int_{|\sigma| > \sigma_c} p(y, \sigma, t) d\sigma. \end{array} \right.$$

If $V(t) \xrightarrow[t \rightarrow +\infty]{} V_\infty$, does $(u; p)$ converge to some (u_∞, p_∞) ?



$$u_\infty = u_\infty(y) = \frac{V_\infty}{L} y, \quad p_\infty = p_\infty(\sigma)$$



Multiscale model: long-time behaviour

Compute u from τ (thus from p):

$$\frac{\partial u}{\partial y}(t, y) = -\frac{1}{\eta} \tau(t, y) + \frac{1}{\eta L} \int_0^L \tau(t, y') dy' + \frac{1}{L} V(t).$$

Insert in the mesoscopic equation

$$\begin{aligned} \frac{\partial p}{\partial t}(t, y, \sigma) &= - \left[-\frac{1}{\eta} \int_{\mathbf{R}} \sigma p(t, y, \sigma) d\sigma + \frac{1}{L} V(t) \right. \\ &\quad \left. + \frac{1}{\eta L} \int_0^L \int_{\mathbf{R}} \sigma p(t, y', \sigma) d\sigma dy' \right] \frac{\partial p}{\partial \sigma}(t, y, \sigma) \\ &\quad + D(p) \frac{\partial^2 p}{\partial \sigma^2}(t, y, \sigma) - H_1 p(t, y, \sigma) + \frac{D(p)}{\alpha} \delta_0, \end{aligned}$$

Family indexed by $y \in]0, L[$ of PDE in (t, σ) coupled through the term

$$\int_0^L \int_{\mathbf{R}} \sigma p(t, y', \sigma) d\sigma dy'.$$



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Multiscale model: long-time behaviour

Theorem (E. Cancès and CLB). For $\rho = 0$.

- Existence and uniqueness. For $V \in H_t^1$ and p_0 such that $D(p_0(y)) > 0$ for all y , the multiscale model has a unique solution $(u; p)$.
- Long-time limit. For α large enough, for V_∞ small enough, for C small enough, if

$$|V(t) - V_\infty| \leq Cf(t) \quad \text{with} \quad |f(t)| \leq 1 \quad \text{and} \quad f(t) \xrightarrow[t \rightarrow +\infty]{} 0,$$

and if p_0 is close enough to p_∞ [unique steady state associated with V_∞/L for which $D(p_\infty) > 0$], then

$$(u(t), p(t)) \xrightarrow[t \rightarrow +\infty]{} (u_\infty; p_\infty) \quad \text{at least in } L_y^1 \times L_{y,\sigma}^1.$$

Discrete and Continuous dynamical Systems B, Vol. 6, No. 3, pp 449-470, 2006,



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Multiscale model: long-time behaviour

The long-time limit is obtained by using the entropy function

$$S_2(y, t) = \int_{\mathbf{R}} \left(\frac{p(t, y, \sigma)}{p_\infty(\sigma)} - 1 \right)^2 p_\infty(\sigma) d\sigma$$

and by writing an equation of the form

$$\frac{d\mathcal{S}}{dt} + \epsilon \mathcal{S} \leq C |V(t) - V_\infty|$$

for the quantity

$$\mathcal{S}(t) = \int_0^L \sqrt{S_2(t, y)} dy$$



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Numerical issues

We recall the mesoscopic equation is a parabolic equation which is

- nonlinear,
- nonlocal,
- possibly degenerate,
- with a singular r.h.s.,
- set on an unbounded domain.

$$\partial_t p = -\partial_\sigma p + D(p) \partial_{\sigma\sigma} p - \chi_{\mathbf{R} \setminus [-\sigma_c, \sigma_c]}(\sigma) p + D(p)\delta_0(\sigma)$$

$$D(p) = \int_{|\sigma| > \sigma_c} p$$

All constants to one, for simplicity.



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Numerical issues

Two approaches

- deterministic: finite-differences in space, operator splitting in time: advection (upwind, Lax-Friedrichs), diffusion (implicit Euler), source (exact)
- stochastic

Question: numerical analysis of time-splitting (say, Strang) for time-dependent operators $e^{S/2}e^{A/2}e^D e^{A/2}e^{S/2}$; Simpler situation, Take advection-diffusion

$$\partial_t p = -\partial_\sigma p + D(p(t), t, \dots)) \partial_{\sigma\sigma} p$$

What is the order of the usual splitting schemes?



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Numerical issues

Stochastic approach: simulate a diffusion process with jumps, nonlinear in the sense of McKean

$$\left\{ \begin{array}{ll} \text{if } |\sigma_{k,i}^n| < \sigma_c, & \text{then } \sigma_{k,i}^{n+1} = \sigma_{k,i}^n + \frac{u_{k+1}^n - u_k^n}{\Delta y} \Delta t + \nu_k^n \sqrt{\Delta t} G_{k,i}^n, \\ \text{otherwise if } \omega_{k,i}^n \in [0, \Delta t] & \text{then } \sigma_{k,i}^{n+1} = 0, \\ \text{otherwise } & \sigma_{k,i}^{n+1} = \sigma_{k,i}^n + \frac{u_{k+1}^n - u_k^n}{\Delta y} \Delta t + \nu_k^n \sqrt{\Delta t} G_{k,i}^n, \end{array} \right.$$

where $\sigma_{k,i}^n$ is the state of constraint of the i -th “particle” at time $n\Delta t$, at the macropoint $(k + 1/2)\Delta y$, and where $D_k^n = \frac{1}{N} \text{Card}\{i / |\sigma_{k,i}^n| > \sigma_c\}$, $\nu_k^n = \sqrt{2\nu D_k^n}$, $G_{k,i}^n$ and $\omega_{k,i}^n$ are two random variables following $\mathcal{N}(0, 1)$ and the uniform law respectively.

Then the stress writes

$$T_k^n = \frac{1}{N} \sum_{i=1}^N \sigma_{k,i}^n.$$

See BenAlaya/Jourdain, J.Appl. Prob., to appear.



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Numerical issues

Solve at each macroscopic point (Gauss point) the mesoscopic equation, a PDE, parameterized by some macroscopic field

$$\partial_t p = -f(y, t) \partial_\sigma p + D(p) \partial_{\sigma\sigma} p - \chi_{\mathbf{R} \setminus [-\sigma_c, \sigma_c]}(\sigma) p + D(p)\delta_0(\sigma)$$

$$(f(y, t) = -G_0 \partial_y u(t, y)).$$

Appropriate framework for [Reduced Basis approaches](#) (Maday/Patera/Rondqvist, Almroth et al. - 1970'-, Noor and Peters -1980'-)

Off-line: Solve the equation for a set of $f(y, t)$

On-line: use the solutions obtained as a basis set for expanding the solution for a general $f(y, t)$

Crucial ingredient: a-posteriori estimators to evaluate the quality of the solution, and possibly extend the basis on demand.

Preliminary tests (by S. Boyaval) on Fokker-Planck for polymeric fluids: very very (very) promising...



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Work in progress

- numerical analysis of the splitting scheme
(dependence in time, issues of regularity)
- clarify mathematically the stochastic approach
(coupled case)
- proceed with the reduced basis technology
- Extend the simulation (and, before, the model!) to dimensions 2 and 3



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