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1 Introduction

A coupled ensemble-based data assimilation system called the POAMA (http://poama.bom.gov.au) Ensemble Coupled Data Assimilation System (PECDAS) has been developed. PECDAS is an approximate form of ensemble Kalman filter system. It is based on the multivariate ensemble optimum interpolation of Oke et al (2005), but uses covariances estimated from a time evolving model ensemble. The first version of the PECDAS is weakly coupled, only ocean observations (T, S) are assimilated into the coupled model and the atmospheric component is nudged towards pre-existing atmospheric analyses (U, V, Q, T from ERA-Interim). A reanalysis from 1980 to present has been completed with this system. Both in situ temperature and salinity observations are assimilated, and ocean current corrections are generated based on the ensemble covariances.

2 System description

PECDAS is a variation of the Ensemble Kalman Filter (EnKF). It includes the routine generation of an ensemble of forecasts, and a state-dependent estimate of the background error covariance. PECDAS differs from traditional EnKF in that only a single analysis is computed for a central forecast. A schematic of a typical integration of PECDAS is presented below.



The construction of the ensemble in PECDAS represents errors in the coupled system through using the coupled model to project the ensemble forward in time. Following the atmospheric nudging and ocean assimilation, the forecast perturbations of each ensemble member are rescaled with respect to the estimated analysis error and centred to the updated central analysis. Considering the different characteristics of the time scales of variability in the ocean and atmosphere and their strong spatial dependence, different rescaling norms that are functions of space are used for each component. Zonally-averaged root mean square difference (RMSD) of 10 m zonal wind (u10) and three dimensional (3-D) RMSD of ocean temperatures have been selected as the atmospheric and oceanic rescaling norms respectively. The rescaling factor for each ensemble member is defined as the ratio of the norm calculated from the estimated analysis error variance and the norm of the forecast perturbations. If the variance of the ensemble perturbations about the central member does not exceed the estimated analysis error variance, then no rescaling for that day is applied. The analysis error of u10 is estimated by the RMSD of u10 between ALI (Hudson et al. 2011) and ERA-40. The 3-D analysis error of oceanic temperature is estimated by the ensemble spread from PEODAS (Yin et al. 2011).

3 Characteristics of the system



References

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climate. However, improvements are seen in terms of both skill and reliability on multi-week timescales. PECDAS will be interfaced with the ACCESS model to form POAMA-3 and that, subject to performance, it should be the Bureau's next operational seasonal prediction model