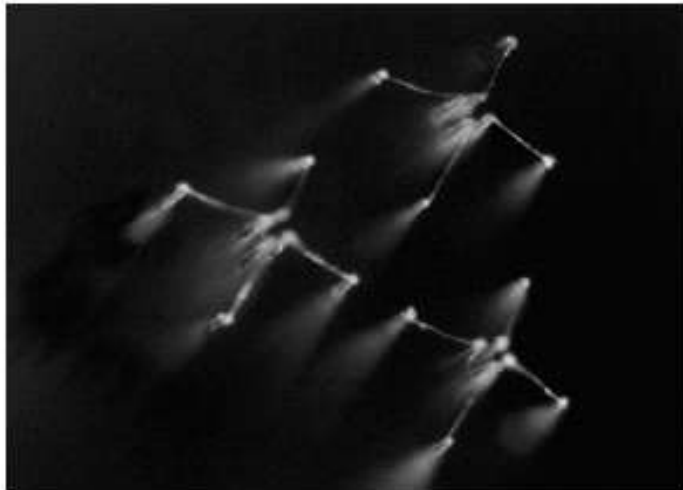


*Fig. 3.1 Hot-wire and hot-film probes. (Photographs provided by and used with permission of TSI, Inc.)*



*Fig. 3.4 Twelve-sensor hot-wire probe to measure velocity and velocity gradient components.*

$$R_s = R_f[1 + \alpha(T_s - T_f)],$$

$$\frac{dQ}{dt} = P - F,$$

which describes the thermal energy balance. Here  $Q$  is the internal energy of the sensor,  $P \equiv IE \equiv I^2 R_s$  is the electrical input power to the sensor, with  $I$  the current through the sensor,  $E$  the voltage drop across the sensor, and  $R_s$  the sensor resistance.

$F$  represents the total rate of heat transferred from the sensor

$$F = q_c + q_p + q_s + q_r,$$

where  $q_c$  is the heat transfer rate due to convection from the sensor by the flow,  $q_p$  is the heat transfer rate due to conduction to the prongs supporting the ends of the sensors,  $q_s$  is the conductive heat transfer rate to the quartz substrate (for hot-films only), and  $q_r$  is the heat transfer rate due to radiation from the sensor.

$$cm \frac{dT_s}{dt} = P(I, T_s) - F(U, T_s),$$

$Q \equiv cmT_s$ , where  $c$  is the specific heat and  $m$  is the mass of the sensor,

## Free convection small when

$$Re_d > 2G_r^{1/3},$$

where the Grashof number,  $G_r \equiv gd^3\beta(T_w - T_f)/\nu^2$ , criterion for neglecting free convection can be stated as

$$\frac{U}{2} \left[ \frac{1}{g\nu\beta(T_w - T_f)} \right]^{1/3} > 1.$$

## Forced Convection Hot-Wire Cooling

$$q_c = hS(T_w - T_f), \quad (3.7)$$

where  $h$  is the convective heat transfer coefficient and  $S = \pi d\ell$  is the surface area of the sensor wire of length  $\ell$  and diameter  $d$ . Unfortunately,  $h$  is *not* a constant;

### Nusselt Number

$$Nu = \frac{hd}{k_f}, \quad (3.8)$$

where  $k_f$  is the thermal conductivity of the fluid.  $Nu$  indicates the difference in the heat transfer rate to the fluid when the fluid is moving compared to what it would be if the fluid were stationary relative to the sensor.

$$N_u = N_u \left( R_{e_d}, P_r, M_a, G_r, K_n, \frac{\ell}{d}, r_T, \gamma, \theta \right), \quad (3.9)$$

where, in addition to the parameters already defined,  $P_r$  is the Prandtl number,  $M_a$  is the Mach number,  $K_n$  is the Knudsen number,  $r_T = (T_w - T_f)/T_f$  is the temperature overheat ratio,  $\gamma$  is the ratio of specific heats of the fluid, and  $\theta$  is the angle between the normal to the axis of the sensor and the velocity vector at the midpoint of the sensor. Fortunately, the effects of  $M_a$ ,  $G_r$ ,  $K_n$ , and  $\ell/d$  are negligible for appropriate choices of operating conditions and sensor dimensions.

(3.9) reduces to

$$N_u = N_u(R_{e_d}, P_r, r_T)$$

*For gas flows with nearly constant  $P_r$*

$$N_u = [M(r_T) + N(r_T)R_{e_d}^n] \left(1 + \frac{r_T}{2}\right)^m \quad \text{King's law of convective cooling}$$

*for  $m = 0$  and substituting expressions above for  $N_u$  and  $q_c$*

$$q_c = (M' + N'U^n) (T_w - T_f)$$

if the *temperature* of the wire is constrained to be constant and the fluid temperature changes are negligible, the heat transfer rate will depend on the local flow velocity alone. Moreover, since  $dT_s/dt \approx 0$  in this case, (3.4) shows that

$$\frac{E^2}{R_w} = (M' + N'U^n) \frac{R_w - R_f}{\alpha R_f} \quad (3.13)$$

or

$$E^2 = A + BU^n, \quad (3.14)$$

where the new constants  $A$  and  $B$  are the products of  $M'$  and  $N'$  with  $(R_w - R_f)/\alpha R_f$ . This is the form in which King's law is usually given.

To account for the sensor wire cooling from the velocity component tangential to the sensor as well as to that from the normal component, an "effective" velocity  $U_e$  is usually assumed, so that (3.14) becomes

$$E^2 = A + BU_e^n. \quad (3.15)$$

## Alternatives to King's Law

the effective velocity  $U_e$  is frequently expressed as a function of a  $q$ th-order polynomial of the voltage  $E$ , as in <sup>2</sup>

$$U_{e_j} = \sum_{m=1}^q A_{mj} E_j^{m-1}, \quad (3.16)$$

where  $A_{mj}$  are the polynomial coefficients for the  $j$ th sensor in a multisensor probe.

### For example

$$U_{e_j}^2 = A_{1j} + A_{2j} E_j + A_{3j} E_j^2 + A_{4j} E_j^3 + A_{5j} E_j^4$$

### Another alternative is to construct a

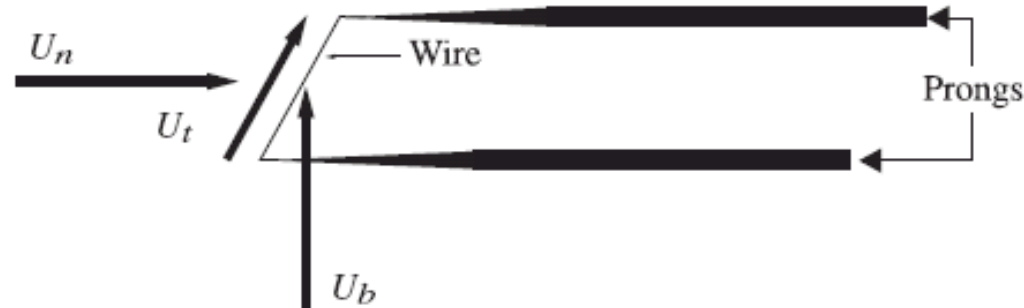
table of ordered values of  $E$ ,  $U_1$ ,  $U_2$ , and  $U_3$  to establish the relationship between the measured voltage and the velocity components, although this does not necessarily have to be single valued.

# Effective Cooling Velocity

velocity vector cooling a hot-wire or hot-film sensor

$$\mathbf{V} = U_n \mathbf{n} + U_b \mathbf{b} + U_t \mathbf{t}, \quad (3.18)$$

where  $\mathbf{n}$ ,  $\mathbf{b}$ , and  $\mathbf{t}$  are unit vectors in the normal, binormal, and tangential directions



*Fig. 3.2 Orientations of normal ( $U_n$ ), tangential ( $U_t$ ), and binormal ( $U_b$ ) velocity components with respect to a hot-wire or hot-film sensor.*

## Jorgensen's cooling law

$$U_e^2 = U_n^2 + h^2 U_b^2 + k^2 U_t^2$$

The value of  $h$  depends on, among other influences, the aerodynamic blockage of the flow by the prongs and is usually close to unity. The value of  $k$  depends on the aspect ratio of the sensor,  $\ell/d$ ; for  $\ell/d \approx 200$ ,  $k \approx 0.2$ .

In the laboratory coordinate system

$$\mathbf{V} = U_1 \mathbf{i} + U_2 \mathbf{j} + U_3 \mathbf{k},$$

Relating the two decompositions of  $\underline{\mathbf{V}}$

$$U_n = n_1 U_1 + n_2 U_2 + n_3 U_3,$$

$$U_b = b_1 U_1 + b_2 U_2 + b_3 U_3,$$

$$U_t = t_1 U_1 + t_2 U_2 + t_3 U_3,$$

where the coefficients  $n_i$ ,  $b_i$ , and  $t_i$  ( $i = 1, 2, 3$ ) can be written in terms of sines and cosines of the angles of inclination of the sensors to the laboratory coordinate system

Substituting  $U_n$ ,  $U_b$ , and  $U_t$

$$U_{e_j}^2 = a_{1_j} U_{1_j}^2 + a_{2_j} U_{2_j}^2 + a_{3_j} U_{3_j}^2 + a_{4_j} U_{1_j} U_{2_j} + a_{5_j} U_{1_j} U_{3_j} + a_{6_j} U_{2_j} U_{3_j}, \quad (3.24)$$

where the coefficients  $a_{n_j}$  ( $n = 1, \dots, 6$ ) are products of the geometry coefficients,  $n_i$ ,  $b_i$ , and  $t_i$ , in (3.21) through (3.23) with the weighting factors,  $h$  and  $k$ , in (3.19).



# Multisensor Probes

## Velocity Component Measurements

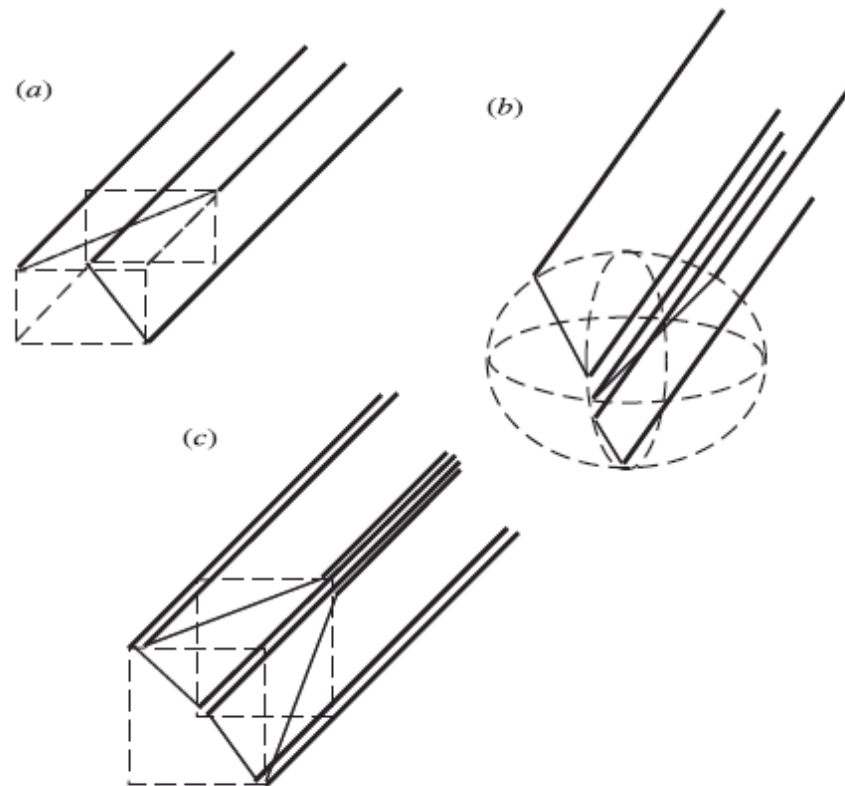


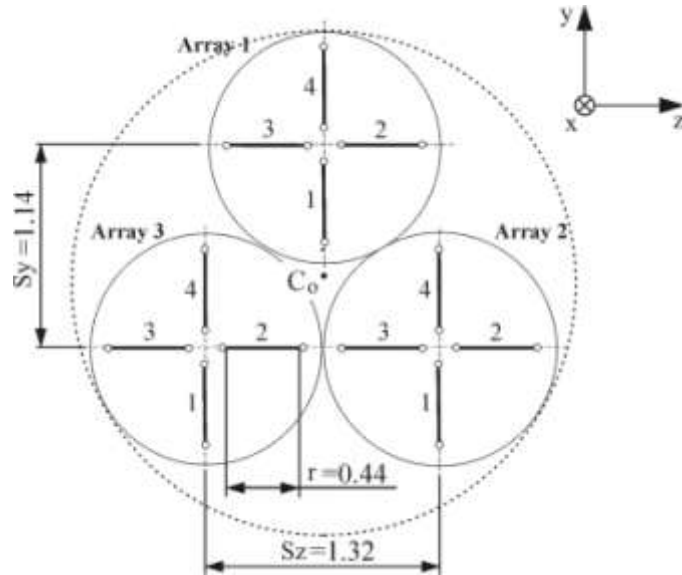
Fig. 3.3 Sketches of (a) two-, (c) three-, and (c) four-sensor hot-wire probes.

### Two component X- or V-array probes

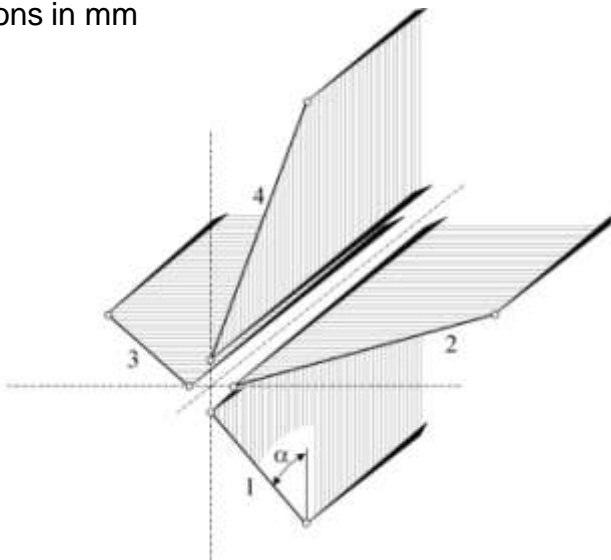
$$a_{1j}U_{1j}^2 + a_{2j}U_{2j}^2 + a_{4j}U_{1j}U_{2j} = A_{1j} + A_{2j}E_j + A_{3j}E_j^2 + A_{4j}E_j^3 + A_{5j}E_j^4$$

( $j = 1, 2$ ) in the two unknown velocity components  $U_1$  and  $U_2$ .

# 12-Sensor Hot-Wire Probe



Dimensions in mm



Vukoslavčević & Wallace. (1996)

Meas. Sci & Tech. 10

# 12-sensor Probe Data Processing for Simultaneous velocity vector and velocity gradient tensor measurements

Taylor's series expansion of velocity components about probe cross-stream plane centroid to center of the jth sensor over the measured distances,  $C_j$  and  $D_j$ .

$$U_{1j} = U_{1_o} + C_j \frac{\partial U_1}{\partial y} + D_j \frac{\partial U_1}{\partial z}$$

$$U_{2j} = U_{2_o} + C_j \frac{\partial U_2}{\partial y} + D_j \frac{\partial U_2}{\partial z}$$

$$U_{3j} = U_{3_o} + C_j \frac{\partial U_3}{\partial y} + D_j \frac{\partial U_3}{\partial z}$$

12 Cooling equations for each of the j sensors in terms of the three velocity components at the probe centroid and the six velocity gradients in the cross-stream plane.

$$f_j \equiv - [P_j] + U_{1_o}^2 + 2C_j U_{1_o} \frac{\partial U_1}{\partial y} + 2D_j U_{1_o} \frac{\partial U_1}{\partial z}$$

$$- k_{2j} \left[ U_{2_o}^2 + 2C_j U_{2_o} \frac{\partial U_2}{\partial y} + 2D_j U_{2_o} \frac{\partial U_2}{\partial z} \right]$$

$$- k_{3j} \left[ U_{3_o}^2 + 2C_j U_{3_o} \frac{\partial U_3}{\partial y} + 2D_j U_{3_o} \frac{\partial U_3}{\partial z} \right]$$

$$- k_{4j} \left[ U_{1_o} U_{2_o} + C_j \left( U_{1_o} \frac{\partial U_2}{\partial y} + U_{2_o} \frac{\partial U_1}{\partial y} \right) + D_j \left( U_{1_o} \frac{\partial U_2}{\partial z} + U_{2_o} \frac{\partial U_1}{\partial z} \right) \right]$$

$$- k_{5j} \left[ U_{1_o} U_{3_o} + C_j \left( U_{1_o} \frac{\partial U_3}{\partial y} + U_{3_o} \frac{\partial U_1}{\partial y} \right) + D_j \left( U_{1_o} \frac{\partial U_3}{\partial z} + U_{3_o} \frac{\partial U_1}{\partial z} \right) \right]$$

$$- k_{6j} \left[ U_{2_o} U_{3_o} + C_j \left( U_{2_o} \frac{\partial U_3}{\partial y} + U_{3_o} \frac{\partial U_2}{\partial y} \right) + D_j \left( U_{2_o} \frac{\partial U_3}{\partial z} + U_{3_o} \frac{\partial U_2}{\partial z} \right) \right] = 0$$

$$P_j = A_{1j} + A_{2j} E_j + A_{3j} E_j^2 + A_{4j} E_j^3 + A_{5j} E_j^4$$

is a **polynomial** of the measured voltages,  $E_j$ .

**120 calibration coefficients**,  $A_{ij}$  and  $k_{ij}$  to be determined .

**System of equations solved by minimizing the error function  $\sum f_j=0$  iteratively at each time step.**

## System of equations for 12-sensor probe in terms of error function $f_j$

$$\begin{aligned}
 f_j \equiv & -P_j + U_{1_o}^2 + 2C_j U_{1_o} \frac{\partial U_1}{\partial y} + 2D_j U_{1_o} \frac{\partial U_1}{\partial z} \\
 & - k_{2j} \left[ U_{2_o}^2 + 2C_j U_{2_o} \frac{\partial U_2}{\partial y} + 2D_j U_{2_o} \frac{\partial U_2}{\partial z} \right] \\
 & - k_{3j} \left[ U_{3_o}^2 + 2C_j U_{3_o} \frac{\partial U_3}{\partial y} + 2D_j U_{3_o} \frac{\partial U_3}{\partial z} \right] \tag{3.29} \\
 & - k_{4j} \left[ U_{1_o} U_{2_o} + C_j \left( U_{1_o} \frac{\partial U_2}{\partial y} + U_{2_o} \frac{\partial U_1}{\partial y} \right) + D_j \left( U_{1_o} \frac{\partial U_2}{\partial z} + U_{2_o} \frac{\partial U_1}{\partial z} \right) \right] \\
 & - k_{5j} \left[ U_{1_o} U_{3_o} + C_j \left( U_{1_o} \frac{\partial U_3}{\partial y} + U_{3_o} \frac{\partial U_1}{\partial y} \right) + D_j \left( U_{1_o} \frac{\partial U_3}{\partial z} + U_{3_o} \frac{\partial U_1}{\partial z} \right) \right] \\
 & - k_{6j} \left[ U_{2_o} U_{3_o} + C_j \left( U_{2_o} \frac{\partial U_3}{\partial y} + U_{3_o} \frac{\partial U_2}{\partial y} \right) + D_j \left( U_{2_o} \frac{\partial U_3}{\partial z} + U_{3_o} \frac{\partial U_2}{\partial z} \right) \right] \\
 & = 0,
 \end{aligned}$$

where  $k_{nj} = a_{nj}/a_{1j}$ ,  $n = 2, \dots, 6$ ,  $j = 1, \dots, 12$ , and  $P_j$  is the right-hand side of (3.25). The system of equations (3.29) can be solved at each time step by minimizing the error function given by  $\sum f_j^2$  using Newton's method.

**Taylor's Frozen Turbulence Hypothesis**  
**to determine streamwise gradients**

$$\frac{dU_i}{dx} = -\frac{1}{U_c} \frac{dU_i}{dt}$$

**setting the acceleration equal to zero in the N-S equations**

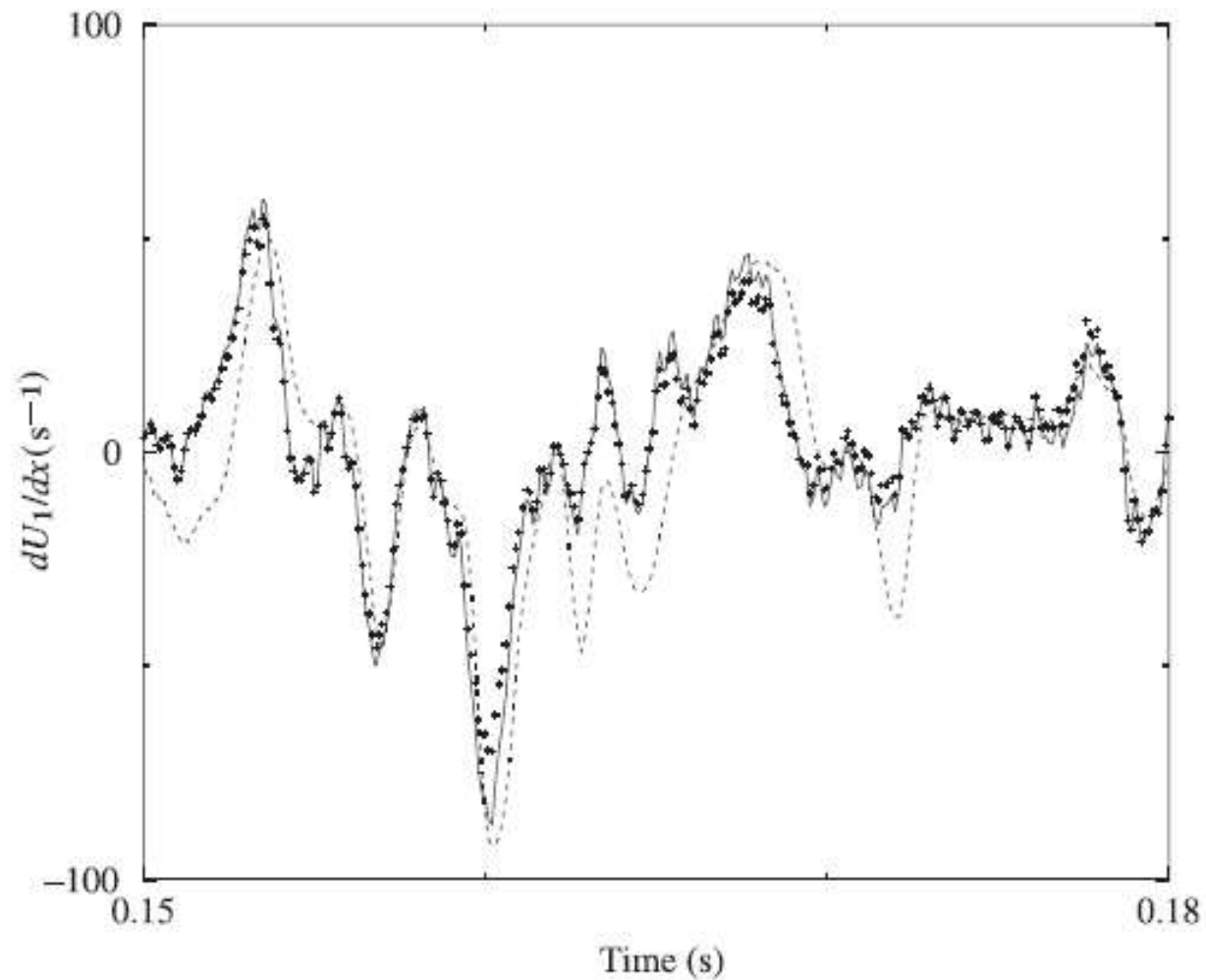
$$\frac{\partial U_i}{\partial t} + U_1 \frac{\partial U_i}{\partial x} + U_2 \frac{\partial U_i}{\partial y} + U_3 \frac{\partial U_i}{\partial z} = 0.$$

Rearranging (3.31) yields

$$\frac{\partial U_i}{\partial x} = -\frac{1}{U_1} \left( \frac{\partial U_i}{\partial t} + U_2 \frac{\partial U_i}{\partial y} + U_3 \frac{\partial U_i}{\partial z} \right).$$

**Streamwise wavenumber approximated from frequency**

$$k_x \approx \frac{2\pi f}{U_1}$$



*Fig. 3.5 Comparison of time-series signals determined from Taylor's hypothesis [Eqs. (3.30) — and (3.32) +++] and from the continuity equation (···) using mixing-layer data from a 12-sensor probe. (From [31].)*

# Constant-Current Operation

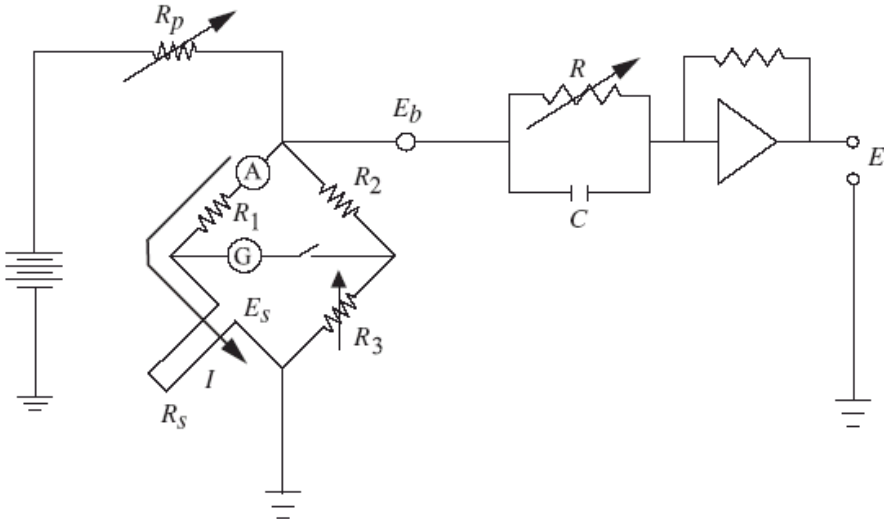


Fig. 3.6 Constant-current hot-wire anemometer circuit. (Adapted from [38].)

# Constant-Temperature Operation

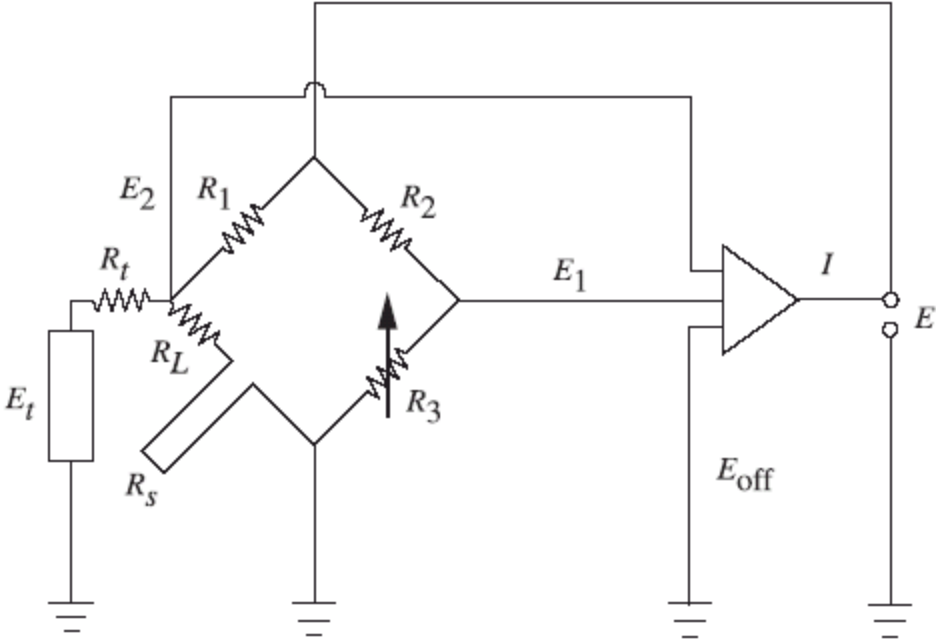


Fig. 3.7 Constant-temperature hot-wire anemometer circuit. (Adapted from [8].)

# Study of Spatial Resolution Effects using DNS

P. V. Vukoslavčević · N. Beratlis · E. Balaras ·  
J. M. Wallace · O. Sun

Exp Fluids

DOI 10.1007/s00348-008-0544-y

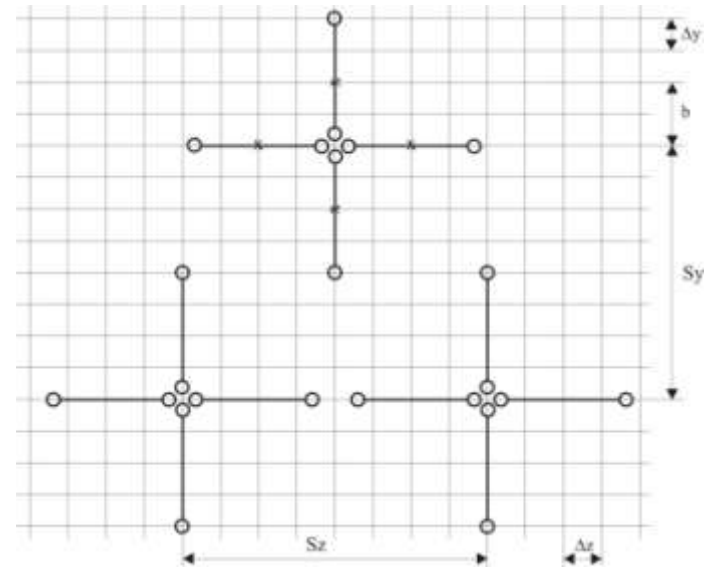
## Virtual experiment

**Database:** DNS of a minimal channel flow at  
 $Re_\tau = 200$

**Grid resolution:**  $\Delta x^+ = \Delta y^+ = \Delta z^+ = 1$   
( $400 \times 192 \times 400$ )

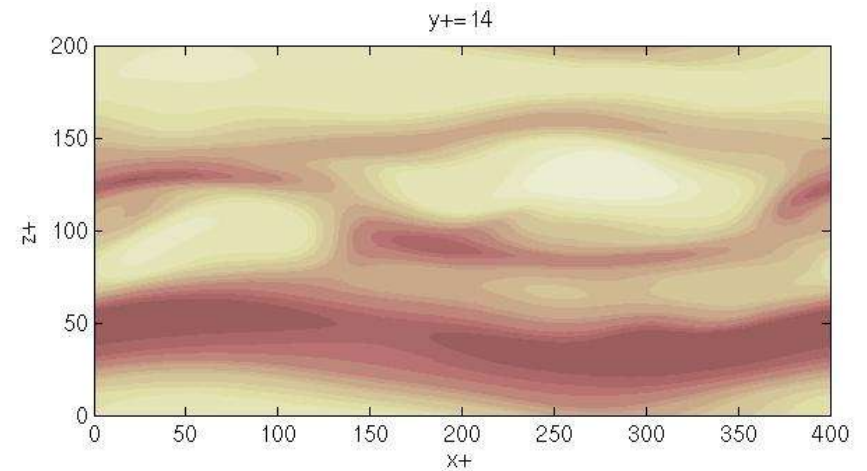
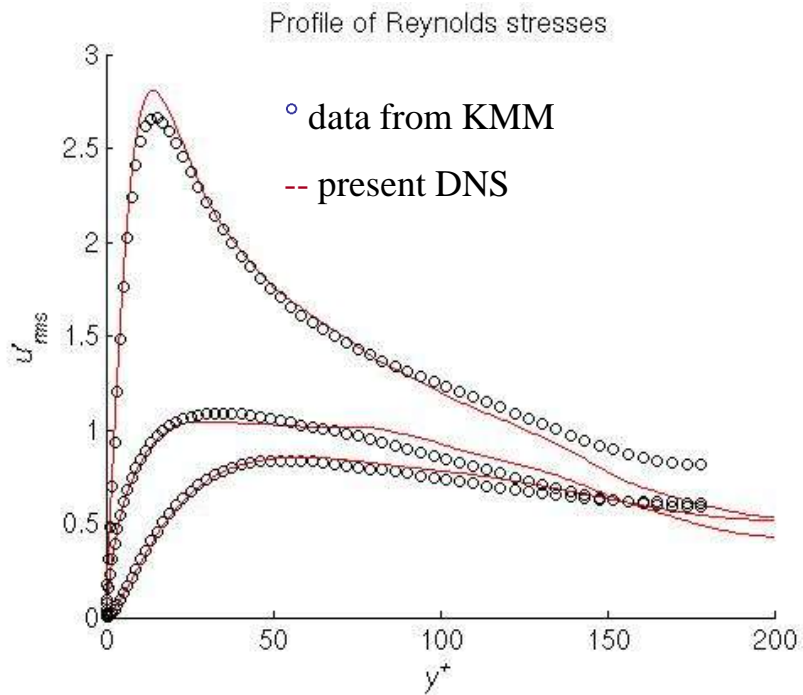
**Virtual probe with  $S_y = 8 \Delta y$  over the numerical grid  
where  $\Delta y$  is 1 viscous length**

$$S_y^+ = 2, 4, 8, 12$$

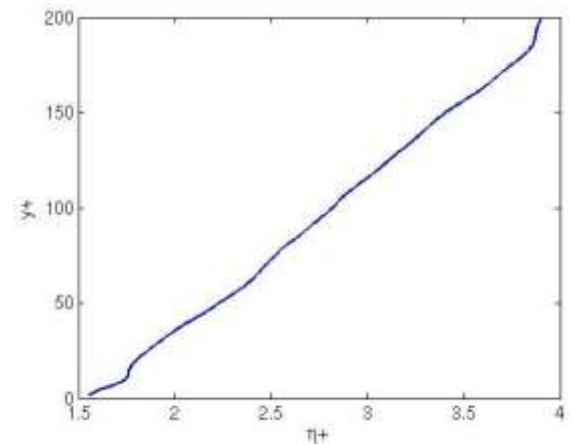




# DNS database

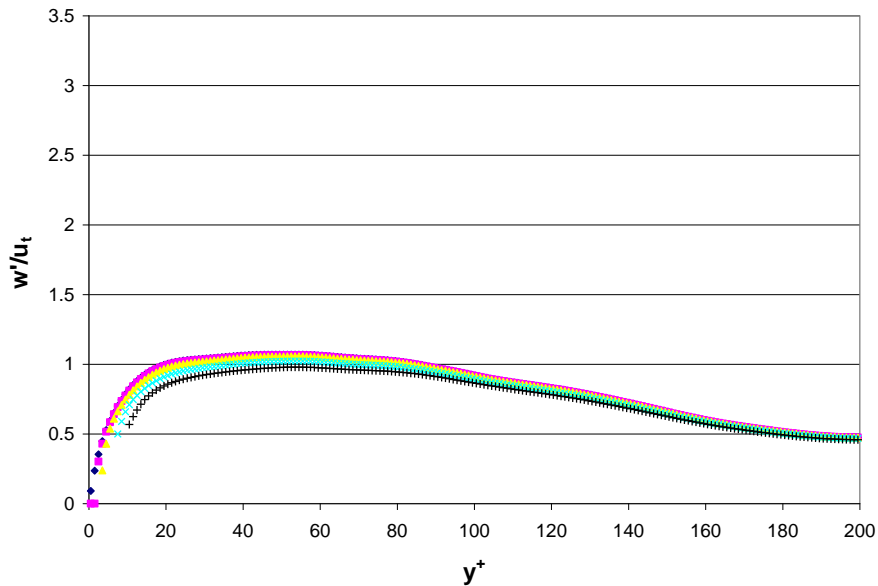
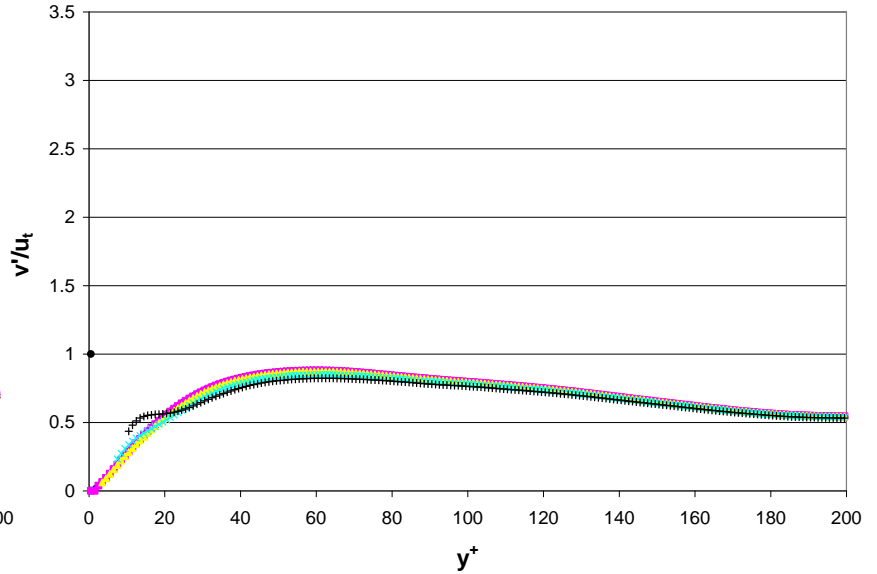
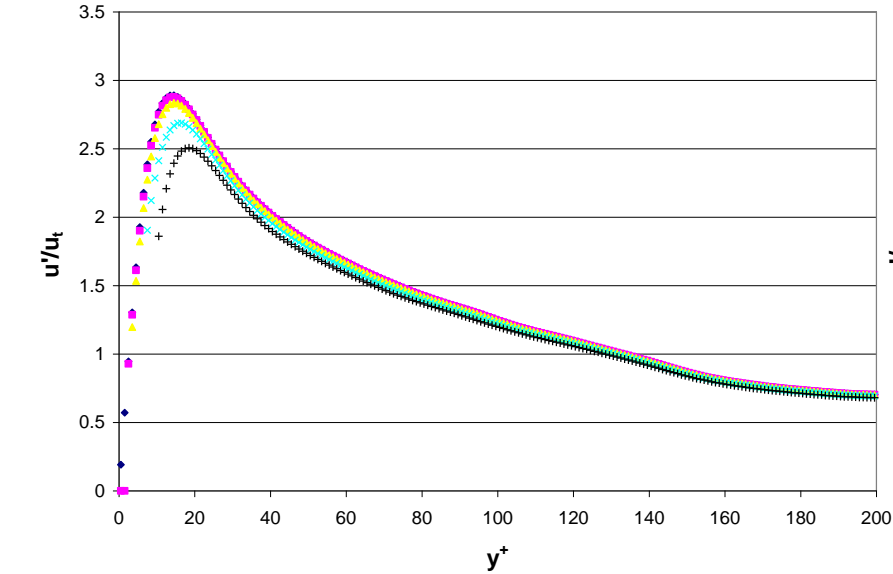


**High and low speed streaks at an instant in time, in a plane parallel to the wall at  $y^+=14$**



**Ratio of Kolmogorov to viscous length scale**

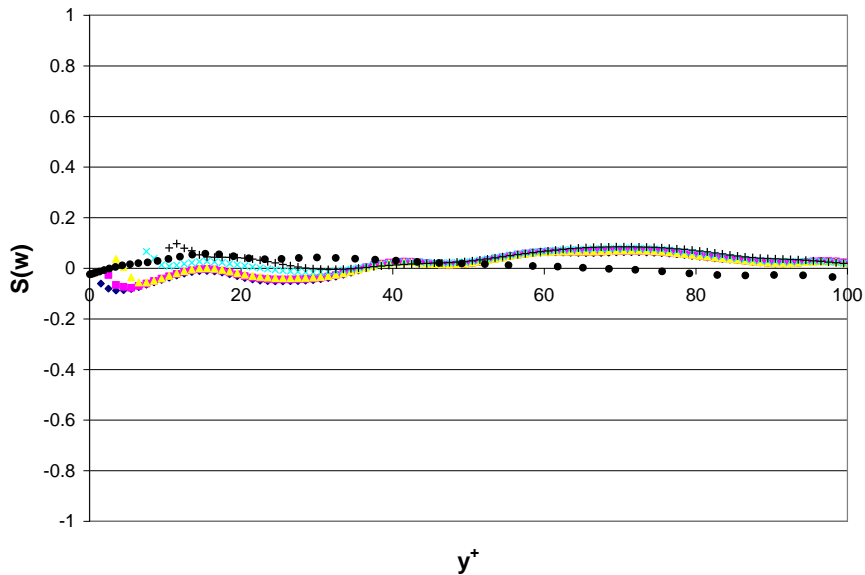
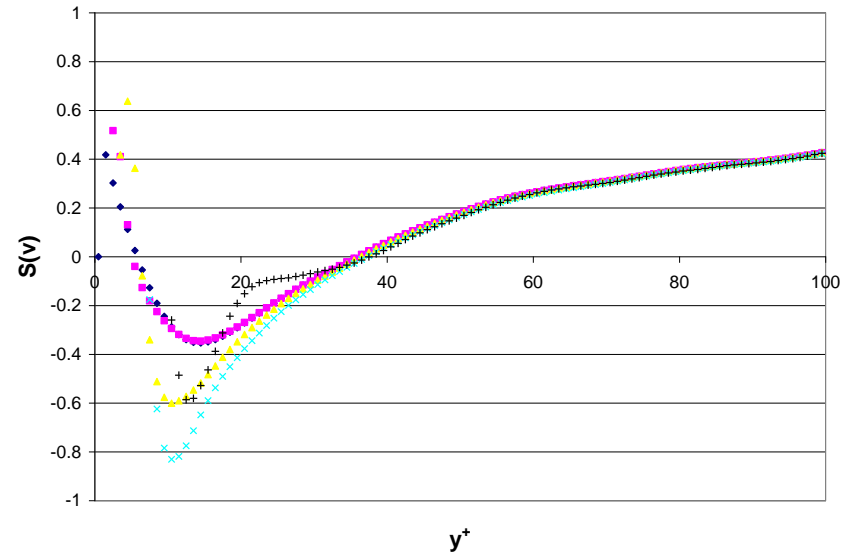
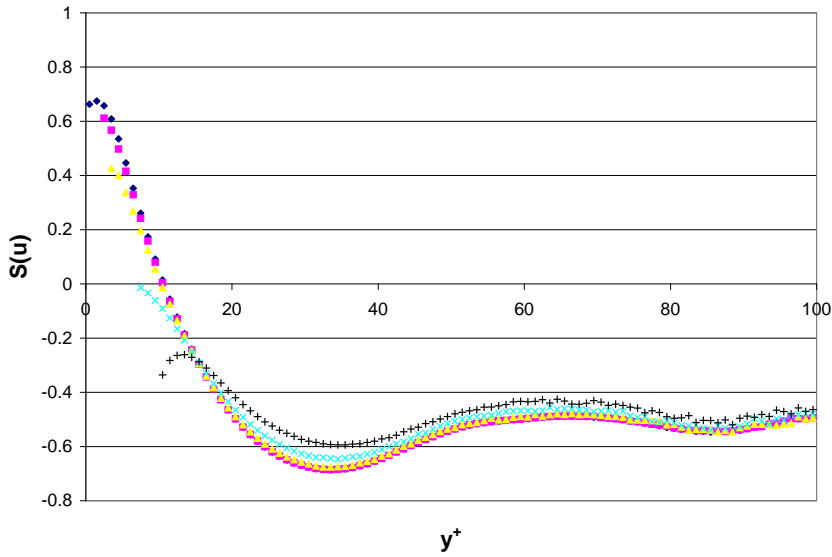
# Velocity Statistics - RMS



◆ DNS

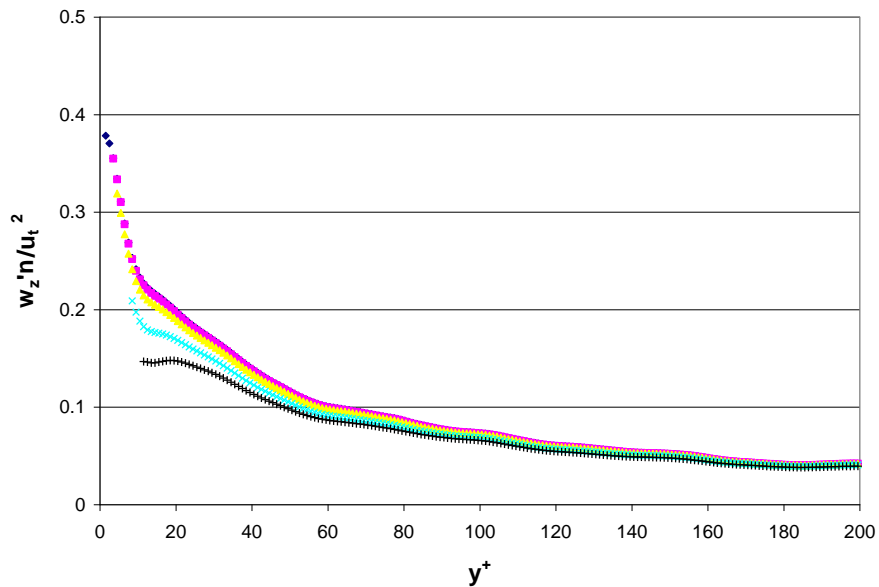
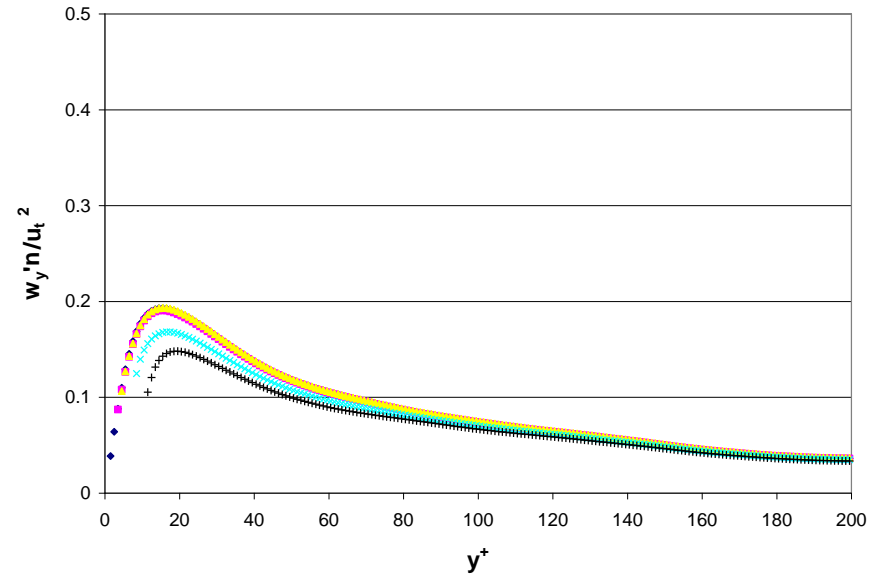
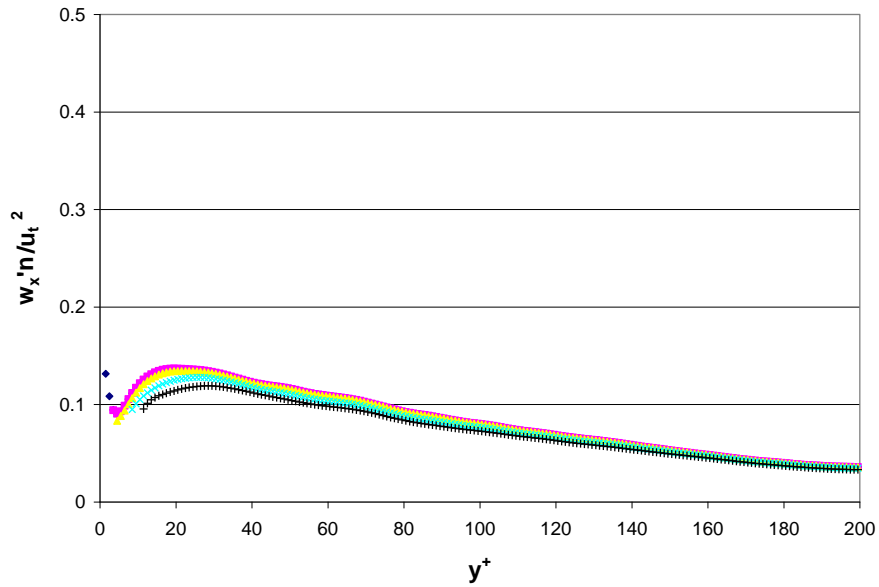
	$y^+ = 15$	$y^+ = 150$
■ S+=2	→ 1.2 $\eta$	→ 0.6 $\eta$
▲ S+=4	→ 2.4 $\eta$	→ 1.2 $\eta$
× S+=8	→ 4.8 $\eta$	→ 2.4 $\eta$
+ S+=12	→ 7.2 $\eta$	→ 3.6 $\eta$

# Velocity Skewness



- ◆ DNS
- $S^+ = 2 \rightarrow 1.2 \eta \rightarrow 0.6 \eta$
- ▲  $S^+ = 4 \rightarrow 2.4 \eta \rightarrow 1.2 \eta$
- ×  $S^+ = 8 \rightarrow 4.8 \eta \rightarrow 2.4 \eta$
- +  $S^+ = 12 \rightarrow 7.2 \eta \rightarrow 3.6 \eta$

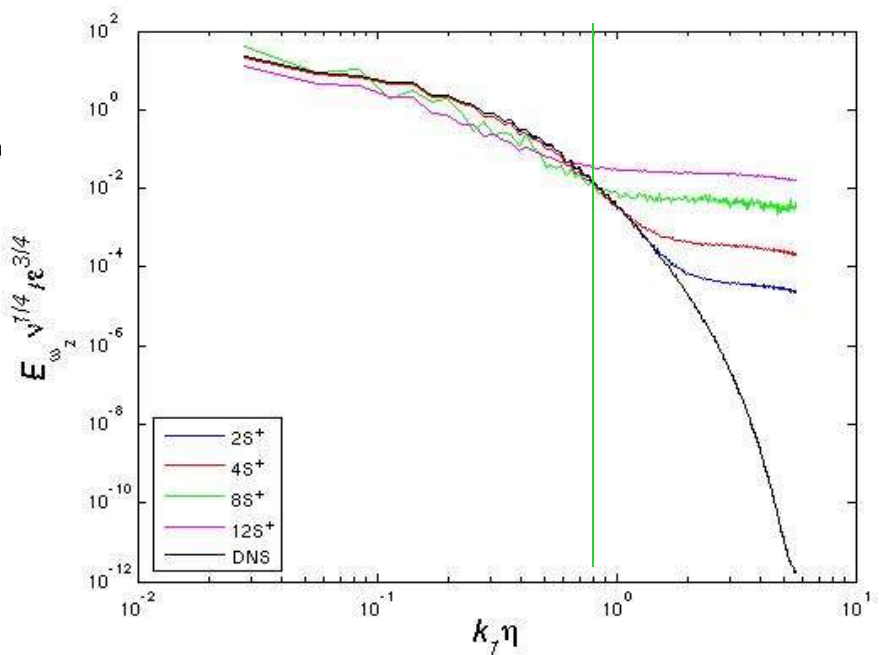
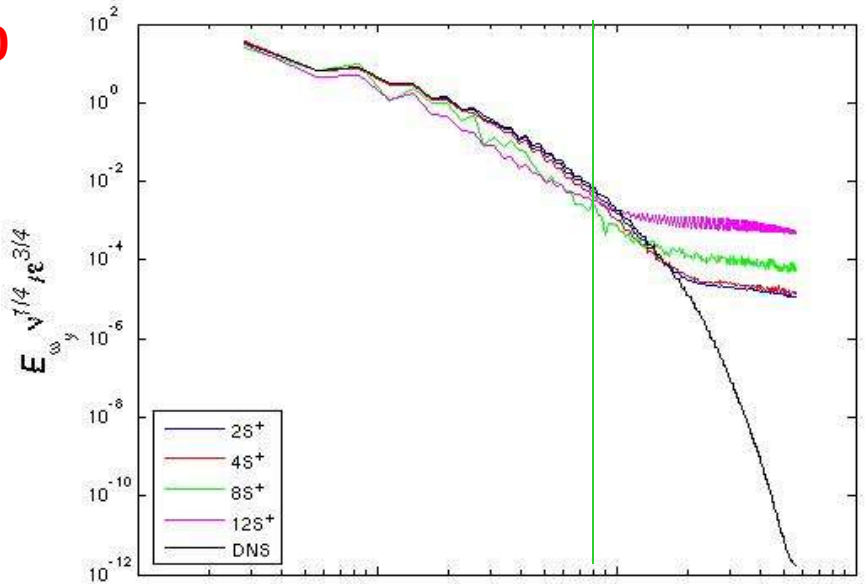
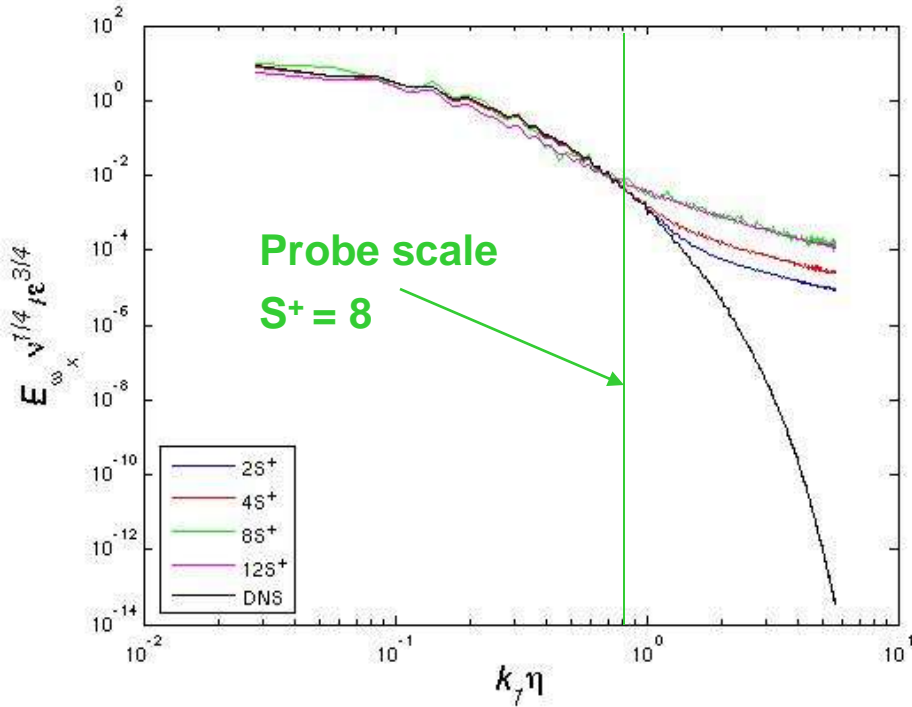
# Vorticity Statistics - RMS



- ◆ DNS
- |            | $y^+ = 15$ |            | $= 150$      |
|------------|------------|------------|--------------|
| ■ $S^+=2$  | →          | $1.2 \eta$ | → $0.6 \eta$ |
| ▲ $S^+=4$  | →          | $2.4 \eta$ | → $1.2 \eta$ |
| × $S^+=8$  | →          | $4.8 \eta$ | → $2.4 \eta$ |
| + $S^+=12$ | →          | $7.2 \eta$ | → $3.6 \eta$ |

# Vorticity Spectra

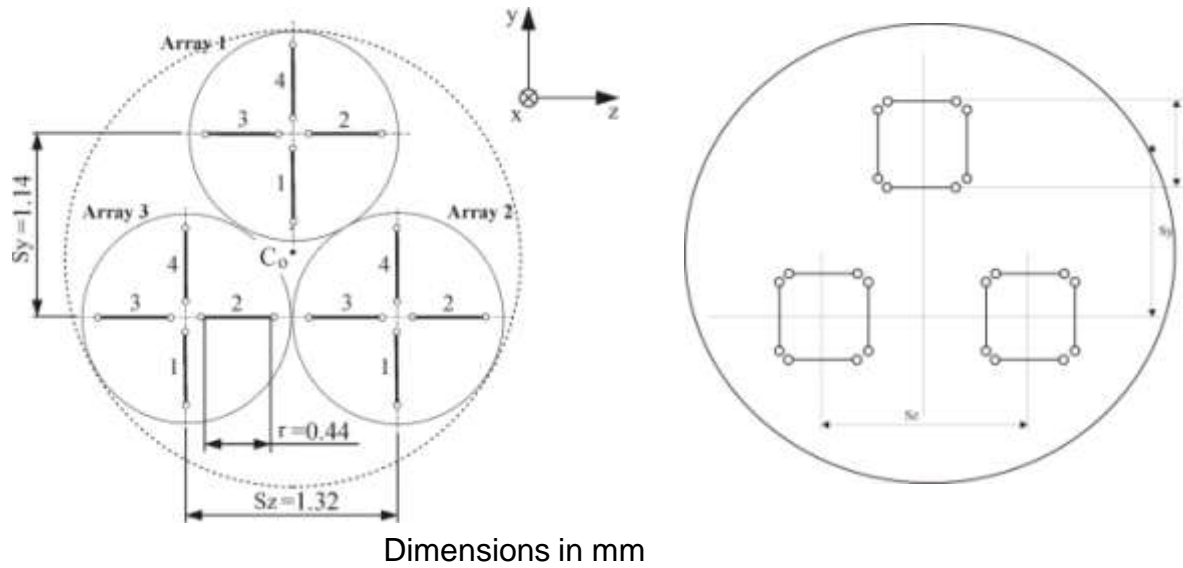
@  $y^+ = 20$



— DNS

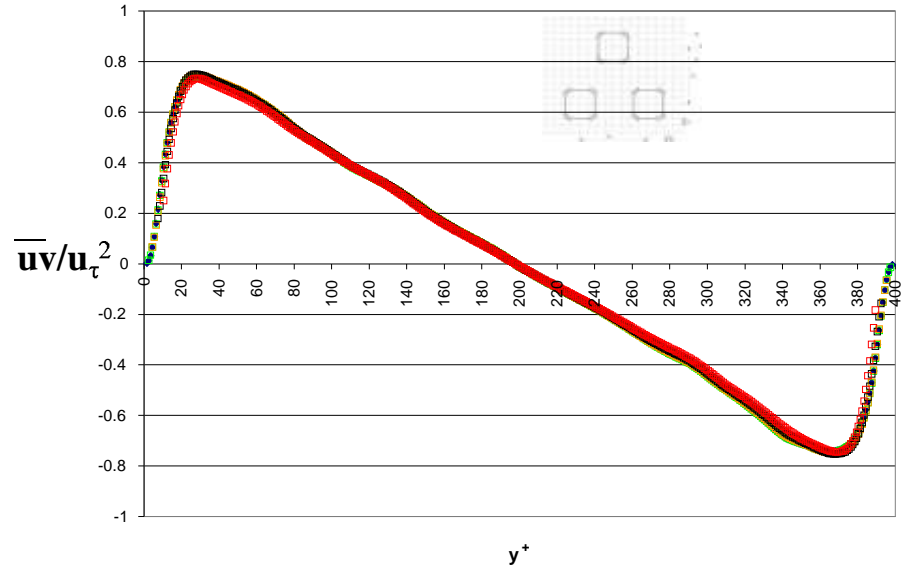
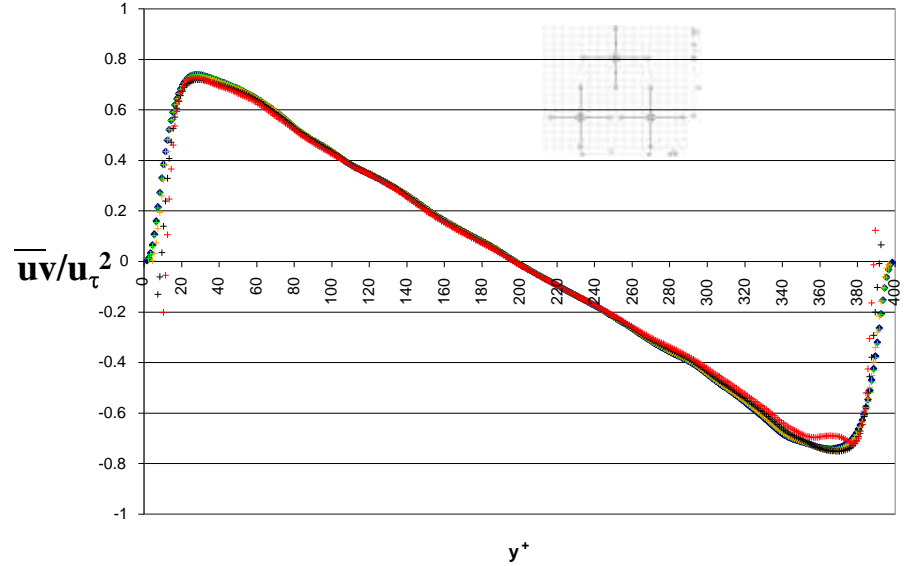
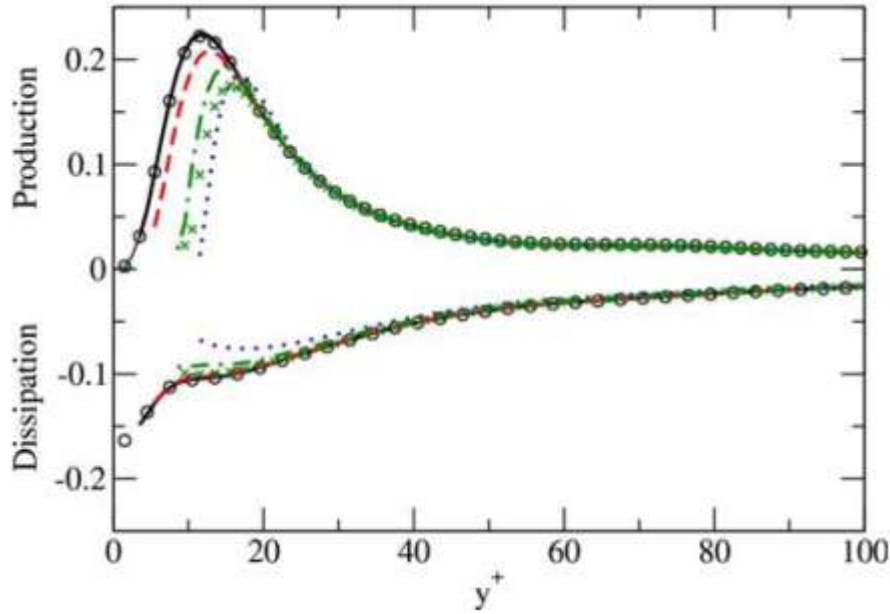
	$y^+ = 15$		$= 150$
— $S^+ = 2$	$\rightarrow 1.2 \eta$	$\rightarrow$	$0.6 \eta$
— $S^+ = 4$	$\rightarrow 2.4 \eta$	$\rightarrow$	$1.2 \eta$
— $S^+ = 8$	$\rightarrow 4.8 \eta$	$\rightarrow$	$2.4 \eta$
— $S^+ = 12$	$\rightarrow 7.2 \eta$	$\rightarrow$	$3.6 \eta$

# 12-sensor hot-wire probes



Plus and square configuration of 12- sensor probes to measure velocity and velocity gradient properties of turbulent flows

# Turbulent Kinetic Energy Production & Dissipation and Reynolds shear stress



◆ DNS

$y^+ = 15 \quad = 150$

+ □  $S^+=2 \rightarrow 1.2 \eta \rightarrow 0.6 \eta$

+ □  $S^+=4 \rightarrow 2.4 \eta \rightarrow 1.2 \eta$

+ □  $S^+=8 \rightarrow 4.8 \eta \rightarrow 2.4 \eta$

+ □  $S^+=12 \rightarrow 7.2 \eta \rightarrow 3.6 \eta$