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# Novel entropy stable schemes for 1D and 2D fluid equations

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**Summary.** We present a systematic study of the novel entropy stable approximations of a variety of nonlinear conservation laws, from the scalar Burgers equation to 1D Navier-Stokes and 2D shallow water equations. This new family of second-order difference schemes avoid using artificial numerical viscosity in the sense that their entropy dissipation is dictated solely by physical dissipation terms. The numerical results of 1D compressible Navier-Stokes equations provide us a remarkable evidence for different roles of viscosity and heat conduction in forming sharp monotone profiles in the immediate neighborhoods of shocks and contacts. Further implementation in 2D shallow water equations is realized dimension by dimension.

## 1 The Inviscid Burgers' Equation

### 1.1 Entropy conservative schemes

We begin with the inviscid Burgers equation,

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x} f(u) = 0, \quad f(u) = \frac{1}{2}u^2. \quad (1)$$

It is equipped with a family of entropy functions,  $U_p(u) = u^{2p}$ ,  $p = 1, 2, \dots$ , such that solutions of (1) satisfy, at the *formal* level,

$$\frac{\partial}{\partial t} U_p(u) + \frac{\partial}{\partial x} F_p(u) = 0. \quad (2)$$

These are additional conservation laws balanced by the corresponding entropy flux functions  $F_p(u) = 2pu^{2p+1}/(2p+1)$ . Spatial integration then yields (ignoring boundary contributions)

$$\int_x u^{2p}(x, t) dx = \int_x u^{2p}(x, 0) dx. \quad (3)$$

We turn to the discrete framework. Discretization in space yields the semi-discrete scheme,

$$\frac{d}{dt} u_\nu(t) + \frac{1}{\Delta x} (f_{\nu+\frac{1}{2}} - f_{\nu-\frac{1}{2}}) = 0. \quad (4)$$

Here,  $u_\nu(t)$  denotes the discrete solution along the gridline  $(x_\nu, t)$  with  $x_\nu := \nu \Delta x$ ,  $\Delta x$  being the uniform meshsize, and  $f_{\nu+\frac{1}{2}} := f(u_{\nu-r+1}, \dots, u_{\nu+r})$  is a consistent numerical flux based on a stencil of  $2r+1$  neighboring grid values, that makes (4) conservative in the sense that  $\sum_\nu u_\nu(t) \Delta x = \sum_\nu u_\nu(0) \Delta x$ . Fix  $p$ . We seek a semi-discrete scheme that conserves the entropy  $U_p(u) = u^{2p}$  in the sense of satisfying the discrete analogue of (2)<sub>p</sub>,

$$\frac{d}{dt} U_p(u_\nu(t)) + \frac{1}{\Delta x} (F_{\nu+\frac{1}{2}} - F_{\nu-\frac{1}{2}}) = 0.$$

Here,  $F_{\nu+\frac{1}{2}}$  is a consistent numerical entropy flux. According to [Ta1987, Theorem 5.2], such 3-point scalar *entropy conservative* schemes are uniquely determined by the entropy conservative numerical flux  $f_{\nu+\frac{1}{2}} = f_{\nu+\frac{1}{2}}^*$  given by,

$$f_{\nu+\frac{1}{2}} = f_{\nu+\frac{1}{2}}^* = \frac{2p-1}{2(2p+1)} \cdot u_\nu^2 \cdot \frac{(u_{\nu+1}/u_\nu)^{2p+1} - 1}{(u_{\nu+1}/u_\nu)^{2p-1} - 1}. \quad (5)$$

The resulting scheme (4), (5) is entropy conservative in the sense that the discrete analogue of total entropy conservation (3) is satisfied,

$$\sum_\nu u_\nu^{2p}(t) \Delta x = \sum_\nu u_\nu^{2p}(0) \Delta x$$

Of course, all the above manipulations are at the formal level. To recover the physical relevant *entropy inequality*,  $\partial_t U_p(u) + \partial_x F_p(u) \leq 0$ , one can add numerical dissipation,

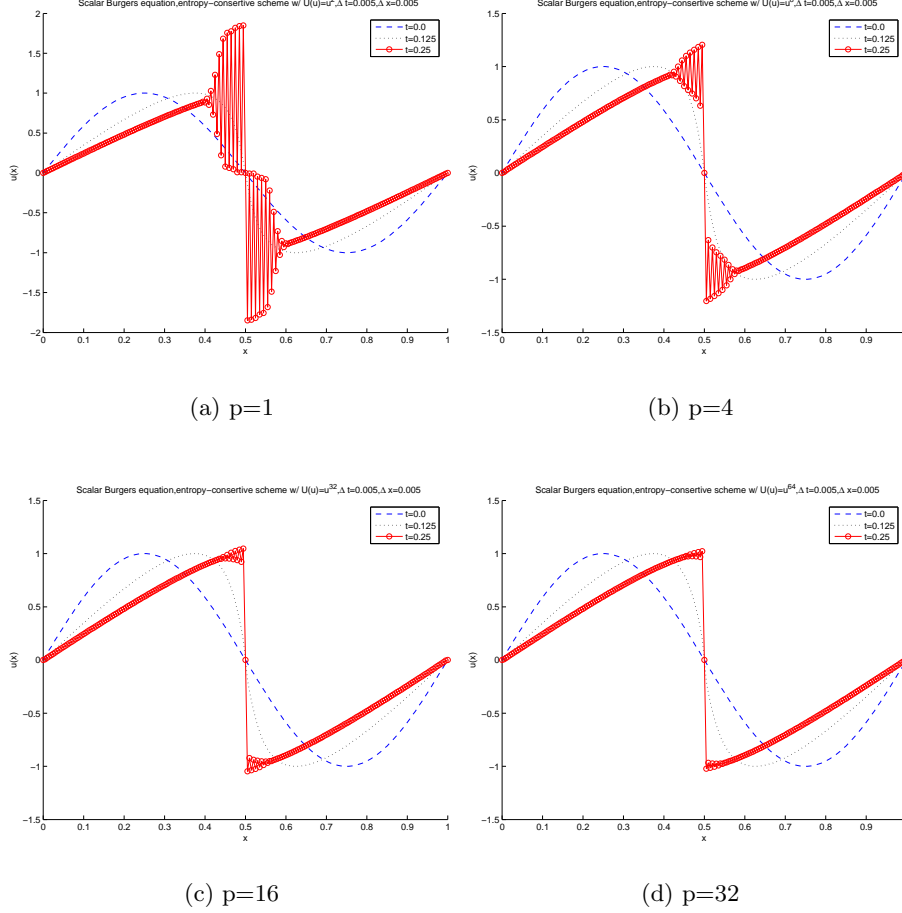
$$\frac{d}{dt} u_\nu(t) + \frac{1}{\Delta x} (f_{\nu+\frac{1}{2}}^* - f_{\nu-\frac{1}{2}}^*) = \frac{\epsilon}{(\Delta x)^2} (d(u_{\nu+1}) - 2d(u_\nu) + d(u_{\nu-1})), \quad \epsilon > 0.$$

This serves as an approximation to the vanishing viscosity regularization  $u_t + f(u)_x = \epsilon d(u)_{xx}$ ,  $d'(u) > 0$ . Sum this scheme against  $v_\nu := U_p'(u_\nu) = 2pu^{2p-1}$ : the resulting entropy balance that follows reads,

$$\frac{d}{dt} \sum_\nu U_p(u_\nu(t)) \Delta x = -\frac{\epsilon}{\Delta x} \sum_\nu \frac{\Delta d_{\nu+\frac{1}{2}}}{\Delta v_{\nu+\frac{1}{2}}} (\Delta v_{\nu+\frac{1}{2}})^2 \leq 0, \quad (6)$$

since  $\frac{\Delta d_{\nu+\frac{1}{2}}}{\Delta v_{\nu+\frac{1}{2}}} := \frac{d(u_{\nu+1}) - d(u_\nu)}{v_{\nu+1} - v_\nu} > 0$  for  $d'(u) > 0$ . Observe that the amount of entropy dissipation on the right is completely determined by the dissipation

term  $\epsilon d(u)$ . No artificial viscosity is introduced by the convective term. If we exclude any dissipative mechanism ( $\epsilon = 0$ ), the entropy conservative solutions admit dispersive oscillations interesting for their own sake, consult [La1986, LL1996].



**Fig. 1.** Scalar Burger's equation, sine initial condition, entropy-conservative schemes, 200 spatial grids,  $U(u) = u^{2p}$ ,  $\Delta t = 5 \times 10^{-3}$ ,  $\Delta x = 5 \times 10^{-3}$

## 1.2 Numerical experiments

The semi-discrete entropy conservative scheme (4),(5) is integrated with the following third-order Runge-Kutta (RK3), consult [GST2001].

$$\begin{aligned}
u^{(1)} &= u^n + \Delta t L(u^n), \\
u^{(2)} &= \frac{3}{4}u^n + \frac{1}{4}u^{(1)} + \frac{1}{4}\Delta t L(u^{(1)}), \\
u^{n+1} &= \frac{1}{3}u^n + \frac{2}{3}u^{(2)} + \frac{2}{3}\Delta t L(u^{(2)}),
\end{aligned} \tag{7}$$

where  $[L(u)]_\nu = -\frac{1}{\Delta x}(f_{\nu+\frac{1}{2}}^* - f_{\nu-\frac{1}{2}}^*)$ . We note that this explicit RK3 time discretization produces a negligible amount of entropy dissipation. For a general framework of entropy conservative fully discrete schemes, consult [LMR2002].

We solve the inviscid Burgers equation with the sine initial condition,  $u(0, x) = \sin(2\pi x)$  and periodic boundary. In **Fig.1**, we display the numerical solutions for (7) with the numerical flux (5) for different choices of  $p$ . Observe that the amplitude of the spurious dispersive oscillations decreases as  $p$  increases. Indeed, as we increase  $p$ , the control of a constant  $U_p$  entropy,  $[\sum_\nu u_\nu^{2p}(t) \Delta x]^{\frac{1}{2p}}$  approaches the control of  $L^\infty$ -norm.

## 2 The 1D Navier-Stokes Equations

### 2.1 Entropy dissipation

We consider the Navier-Stokes equations (NSE) governing the density  $\rho = \rho(x, t)$ , momentum  $m = m(x, t)$ , and energy  $E = E(x, t)$ ,

$$\frac{\partial}{\partial t} \mathbf{u} + \frac{\partial}{\partial x} \mathbf{f}(\mathbf{u}) = \epsilon \frac{\partial^2}{\partial x^2} \mathbf{d}(\mathbf{u}), \quad \mathbf{u} = [\rho, m, E]^\top. \tag{8}$$

They are driven by the convective flux  $\mathbf{f}(\mathbf{u}) = [m, qm + p, q(E + p)]^\top$ , together with the dissipative flux  $\epsilon \mathbf{d}(\mathbf{u}) = (\lambda + 2\mu)[0, q, q^2/2]^\top + \kappa[0, 0, \theta]^\top$  which stands for the combined viscous and heat fluxes. Here,  $\epsilon$  represents the amplitudes of the viscosity and conductivity. These fluxes involve the velocity  $q := m/\rho$ , the pressure  $p = p(x, t) = (\gamma - 1)e$  where  $e := E - \frac{m^2}{2\rho}$ , and the absolute temperature,  $\theta = \theta(x, t) > 0$ , such that  $C_v \rho \theta = e$ . Here  $\gamma > 1$ ,  $\lambda, \mu$  are fixed and  $\kappa \mapsto \kappa/C_v$  with  $C_v = 1$ .

The viscous and heat fluxes are dissipative in the sense that they are responsible for the dissipation of total *entropy*,  $U(\mathbf{u}) = -\rho S$  with  $S = \ln(p\rho^{-\gamma})$  being the specific entropy,

$$\frac{\partial}{\partial t}(-\rho S) + \frac{\partial}{\partial x}(-mS + \kappa(\ln \theta)_x) = -(\lambda + 2\mu)\frac{q_x^2}{\theta} - \kappa\left(\frac{\theta_x}{\theta}\right)^2 \leq 0. \tag{9}$$

Spatial integration of (9) then yields the second law of thermodynamics,

$$\frac{d}{dt} \int_x (-\rho S) dx = -(\lambda + 2\mu) \int_x \frac{q_x^2}{\theta} dx - \kappa \int_x \left(\frac{\theta_x}{\theta}\right)^2 dx \leq 0. \tag{10}$$

In fact, (10) specifies the precise entropy decay rate. In the case of the Euler equations,  $\lambda = \mu = \kappa = 0$ , total entropy is precisely conserved,

$$\int_x -\rho S(x, t) dx = \int_x -\rho S(x, 0) dx.$$

This corresponds to the scalar entropy conservation (3).

## 2.2 Entropy stable schemes for the Navier-Stokes equations

We now turn our attention to the construction of entropy stable schemes for NSE (8). We use the conservative differences for convective flux and standard centered differences for the dissipative terms on the RHS.

$$\frac{d}{dt} \mathbf{u}_\nu(t) + \frac{1}{\Delta x} \left( \mathbf{f}_{\nu+\frac{1}{2}}^* - \mathbf{f}_{\nu-\frac{1}{2}}^* \right) = \frac{\epsilon}{(\Delta x)^2} \left( \mathbf{d}_{\nu+1} - 2\mathbf{d}_\nu + \mathbf{d}_{\nu-1} \right), \quad (11)$$

Here,  $\mathbf{d}_\nu := \mathbf{d}(\mathbf{u}_\nu)$ . As in the scalar case, we seek entropy conservative flux  $\mathbf{f}_{\nu+\frac{1}{2}}^*$ , so that the entropy decay will be dictated *solely* by the dissipation terms on the right of (11). The construction of the entropy conservative flux  $\mathbf{f}_{\nu+\frac{1}{2}}^*$  follows [Ta2004] and [TZ2006], and is summarized in the following

**Algorithm 1** *If  $\mathbf{u}_\nu = \mathbf{u}_{\nu+1}$  then  $\mathbf{f}_{\nu+\frac{1}{2}}^* = \mathbf{f}(\mathbf{v}_\nu)$ ; else*

- *Set  $\Delta \mathbf{u}_{\nu+\frac{1}{2}} := \mathbf{u}_{\nu+1} - \mathbf{u}_\nu$ . Starting with  $\mathbf{u}_{\nu+\frac{1}{2}}^1 := \mathbf{u}_\nu$ , compute recursively the intermediate states,*

$$\mathbf{u}_{\nu+\frac{1}{2}}^{j+1} = \mathbf{u}_{\nu+\frac{1}{2}}^j + \left\langle \widehat{\ell}_{\nu+\frac{1}{2}}^j, \Delta \mathbf{u}_{\nu+\frac{1}{2}} \right\rangle \widehat{\mathbf{r}}_{\nu+\frac{1}{2}}^j, \quad j = 1, 2, 3, \dots \quad (12)$$

*Here,  $\{\widehat{\ell}_{\nu+\frac{1}{2}}^j\}$  and  $\{\widehat{\mathbf{r}}_{\nu+\frac{1}{2}}^j\}$  are the left and right eigensystems of the Roe matrix  $A(\mathbf{u}_\nu, \mathbf{u}_{\nu+1})$  (see [Roe1981]).*

- *Set  $\mathbf{r}_{\nu+\frac{1}{2}}^j := \mathbf{v}(\mathbf{u}_{\nu+\frac{1}{2}}^{j+1}) - \mathbf{v}(\mathbf{u}_{\nu+\frac{1}{2}}^j)$  and let  $\{\ell^j\}_{j=1}^3$  be the corresponding orthogonal system. Compute the entropy-conservative numerical flux,*

$$\mathbf{f}_{\nu+\frac{1}{2}}^* = (\gamma - 1) \sum_{j=1}^3 \frac{m_{\nu+\frac{1}{2}}^{j+1} - m_{\nu+\frac{1}{2}}^j}{\left\langle \ell_{\nu+\frac{1}{2}}^j, \Delta \mathbf{v}_{\nu+\frac{1}{2}} \right\rangle} \ell_{\nu+\frac{1}{2}}^j, \quad \left\langle \ell_{\nu+\frac{1}{2}}^j, \mathbf{v}_{\nu+\frac{1}{2}}^{j+1} - \mathbf{v}_{\nu+\frac{1}{2}}^j \right\rangle = \delta_{jk} \quad (13)$$

Here,  $\mathbf{v}(\mathbf{u}) := U_{\mathbf{u}}(\mathbf{u}) = [-E/e - S + \gamma + 1, q/\theta, -1/\theta]^\top$  are the entropy variables, and  $\{m^j\}$  are intermediate momentum values along the path. We now arrive at our main result of NSE corresponding to the Burgers statement (6).

**Theorem 1 ([TZ2006], Theorem 3.6).** *The semi-discrete scheme (11) with the entropy conservative numerical flux  $\mathbf{f}_{\nu+\frac{1}{2}}^*$  in (12)-(13) and  $\mathbf{d}(\mathbf{u}_\nu)$  being the dissipative NS flux, is entropy stable in the sense that*<sup>3</sup>

<sup>3</sup> We let  $\widehat{z}_{\nu+\frac{1}{2}} = (z_\nu + z_{\nu+1})/2$  and  $\widetilde{z}_{\nu+\frac{1}{2}} = \sqrt{z_\nu z_{\nu+1}}$ .

$$\begin{aligned}
\frac{d}{dt} \sum_{\nu} [-\rho_{\nu}(t) S_{\nu}(t)] \Delta x &= - \sum_{\nu} \frac{\epsilon}{\Delta x} \left\langle \Delta \mathbf{v}_{\nu+\frac{1}{2}}, \frac{\Delta \mathbf{d}_{\nu+\frac{1}{2}}}{\Delta \mathbf{v}_{\nu+\frac{1}{2}}} \Delta \mathbf{v}_{\nu+\frac{1}{2}} \right\rangle \quad (14) \\
&= - (\lambda + 2\mu) \sum_{\nu} \left( \frac{\Delta q_{\nu+\frac{1}{2}}}{\Delta x} \right)^2 \left( \widehat{1/\theta} \right)_{\nu+\frac{1}{2}} \Delta x \\
&\quad - \kappa \sum_{\nu} \left( \frac{\Delta \theta_{\nu+\frac{1}{2}}}{\Delta x} \right)^2 \left( \widetilde{1/\theta} \right)_{\nu+\frac{1}{2}}^2 \Delta x \leq 0.
\end{aligned}$$

*This statement is a discrete analog of the entropy balance statement (10).*

Here is our main point: we introduce no excessive entropy dissipation due to spurious, *artificial* numerical viscosity. According to (14), the semi-discrete scheme contains the precise amount of numerical viscosity to enforce the correct entropy dissipation dictated by NSE. More can be found in [Ta2004, TZ2006].

### 2.3 Numerical experiments

We consider ideal polytropic gas equations as an approximation of air with

$$\gamma = 1.4, \quad C_v = 716, \quad \kappa = 0.03, \quad \lambda + 2\mu = 2.28 \times 10^{-5}.$$

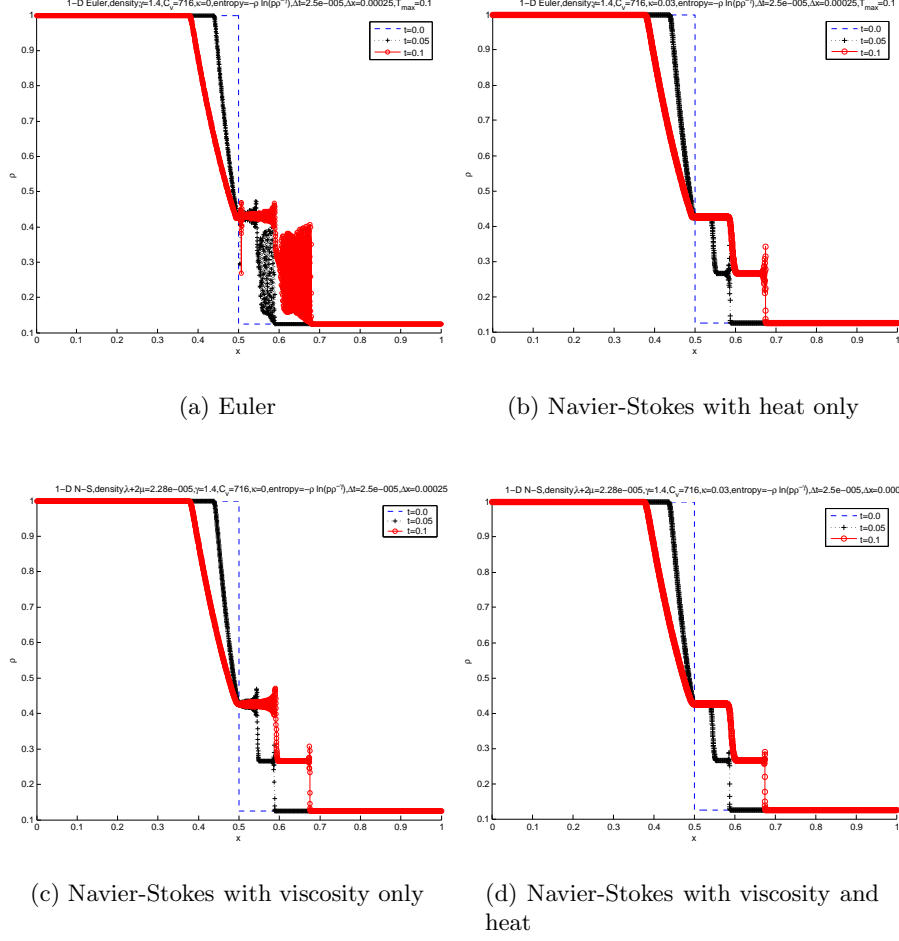
We simulate the Sod's shocktube problem, where the Euler and NSE are solved over the interval  $[0, 1]$  subject to Riemann initial conditions

$$(\rho, m, E)_{t=0} = \begin{cases} (1.0, 0.0, 2.5) & 0 < x \leq 0.5 \\ (0.125, 0.0, 0.25) & 0.5 < x < 1. \end{cases}$$

In **Fig.2**, we display the numerical solutions for the fully discrete scheme (11) with RK3 method (7) and the numerical flux (13). The density fields of four different cases are recorded.

Density field of the Euler equations 2(a) demonstrates the purely dispersive character of the entropy conservative schemes. Dispersive oscillations on the mesh scale are observed in shocks and contact regions due to the absence of any dissipative mechanism. These oscillations approach a modulated wave envelop, consult [La1986, LL1996] for more discussions on dispersive oscillations.

For the results of NSE in 2(b)-2(d), the presence of heat flux causes the oscillations to be dramatically reduced around the contact discontinuity and the shock in 2(b). The viscous flux in NSE, on the other hand, is doing a better job than heat flux in damping oscillations around the shock in 2(c), but we still can observe an oscillatory behavior around the contact discontinuity. In 2(d), not only the oscillations around the shock are damped out by viscosity, but the oscillations around the contact discontinuity are significantly reduced due to the heat flux.



**Fig. 2.** Density field Sod problem with 4000 spatial gridpoints,  $U(\mathbf{u}) = -\rho \ln(p\rho^{-\gamma})$ ,  $\Delta t = 2.5 \times 10^{-5}$ ,  $\Delta x = 2.5 \times 10^{-4}$

### 3 The 2D Shallow Water Equations

We turn to 2D shallow water equations,

$$\frac{\partial}{\partial t} \mathbf{u} + \frac{\partial}{\partial x} \mathbf{f}(\mathbf{u}) + \frac{\partial}{\partial y} \mathbf{g}(\mathbf{u}) = \eta \frac{\partial}{\partial x} \left( h \frac{\partial}{\partial x} \mathbf{d}(\mathbf{u}) \right) + \eta \frac{\partial}{\partial y} \left( h \frac{\partial}{\partial y} \mathbf{d}(\mathbf{u}) \right), \quad (15)$$

with  $\mathbf{u} = [h, uh, vh]^\top$  being the vector of conserved variables balanced by the flux vectors

$$\mathbf{f} = [uh, u^2h + gh^2/2, uvh]^\top, \quad \mathbf{g} = [vh, uvh, v^2h + gh^2/2]^\top,$$

and the viscous flux vector  $\mathbf{d} = [0, u, v]^\top$ . Here,  $h = h(x, t)$  is the total water height,  $(u(x, t), v(x, t))$  are the depth-averaged velocities along  $x$  and  $y$  direction. Finally,  $g$  is the constant acceleration due to gravity, and  $\eta > 0$  is the constant eddy viscosity which models the turbulence stress in the flow.

The total energy  $U(\mathbf{u}) = (gh^2 + u^2h + v^2h)/2$  serves as an entropy function,

$$\frac{\partial}{\partial t}U(\mathbf{u}) + \frac{\partial}{\partial x}F(\mathbf{u}) + \frac{\partial}{\partial y}G(\mathbf{u}) = -\eta h(u_x^2 + u_y^2 + v_x^2 + v_y^2), \quad (16)$$

where  $F(\mathbf{u}) = guh^2 + \frac{u^3h+uv^2h}{2} - huv_x$  and  $G(\mathbf{u}) = gvh^2 + \frac{u^2vh+v^3h}{2} - hvv_y$  are the entropy fluxes. Spatial integration of (16) yields

$$\frac{d}{dt} \int_y \int_x U(\mathbf{u}) dx dy = -\eta \int_y \int_x h(u_x^2 + u_y^2 + v_x^2 + v_y^2) dx dy. \quad (17)$$

For the inviscid case ( $\eta = 0$ ), the global entropy conservation is satisfied,

$$\int_y \int_x U(\mathbf{u}(x, t)) dx dy = \int_y \int_x U(\mathbf{u}(x, 0)) dx dy$$

Arguing along the same line as the above NSE dimension by dimension, we obtain the entropy-stable semi-discrete schemes (recall  $\widehat{z_{\nu+1}} := (z_{\nu+1} + z_\nu)/2$ )

$$\begin{aligned} \frac{d}{dt} \mathbf{u}_{\nu, \mu}(t) &+ \frac{1}{\Delta x} (\mathbf{f}_{\nu+\frac{1}{2}, \mu}^* - \mathbf{f}_{\nu-\frac{1}{2}, \mu}^*) + \frac{1}{\Delta y} (\mathbf{g}_{\nu, \mu+\frac{1}{2}}^* - \mathbf{g}_{\nu, \mu-\frac{1}{2}}^*) \\ &= \frac{\eta}{\Delta x} (\widehat{h_{\nu+\frac{1}{2}, \mu}} \frac{\mathbf{d}_{\nu+1, \mu} - \mathbf{d}_{\nu, \mu}}{\Delta x} - \widehat{h_{\nu-\frac{1}{2}, \mu}} \frac{\mathbf{d}_{\nu, \mu} - \mathbf{d}_{\nu-1, \mu}}{\Delta x}) \\ &\quad + \frac{\eta}{\Delta y} (\widehat{h_{\nu, \mu+\frac{1}{2}}} \frac{\mathbf{d}_{\nu, \mu+1} - \mathbf{d}_{\nu, \mu}}{\Delta x} - \widehat{h_{\nu, \mu-\frac{1}{2}}} \frac{\mathbf{d}_{\nu, \mu} - \mathbf{d}_{\nu, \mu-1}}{\Delta x}), \end{aligned} \quad (18a)$$

with the entropy-conservative fluxes  $\mathbf{f}_{\nu+\frac{1}{2}, \mu}^*$  and  $\mathbf{g}_{\nu, \mu+\frac{1}{2}}^*$  outlined in Algorithm 1 along  $x$  and  $y$  direction, respectively,

$$\mathbf{f}_{\nu+\frac{1}{2}, \mu}^* = \frac{g}{2} \sum_{j=1}^3 \frac{(h_{\nu+\frac{1}{2}, \mu}^{j+1})^2 u_{\nu+\frac{1}{2}, \mu}^{j+1} - (h_{\nu+\frac{1}{2}, \mu}^j)^2 u_{\nu+\frac{1}{2}, \mu}^j}{\langle \ell_{\nu+\frac{1}{2}, \mu}^{x^j}, \Delta \mathbf{v}_{\nu+\frac{1}{2}, \mu} \rangle} \ell_{\nu+\frac{1}{2}, \mu}^{x^j}, \quad (18b)$$

$$\mathbf{g}_{\nu, \mu+\frac{1}{2}}^* = \frac{g}{2} \sum_{j=1}^3 \frac{(h_{\nu, \mu+\frac{1}{2}}^{j+1})^2 u_{\nu, \mu+\frac{1}{2}}^{j+1} - (h_{\nu, \mu+\frac{1}{2}}^j)^2 u_{\nu, \mu+\frac{1}{2}}^j}{\langle \ell_{\nu, \mu+\frac{1}{2}}^{y^j}, \Delta \mathbf{v}_{\nu, \mu+\frac{1}{2}} \rangle} \ell_{\nu, \mu+\frac{1}{2}}^{y^j}, \quad (18c)$$

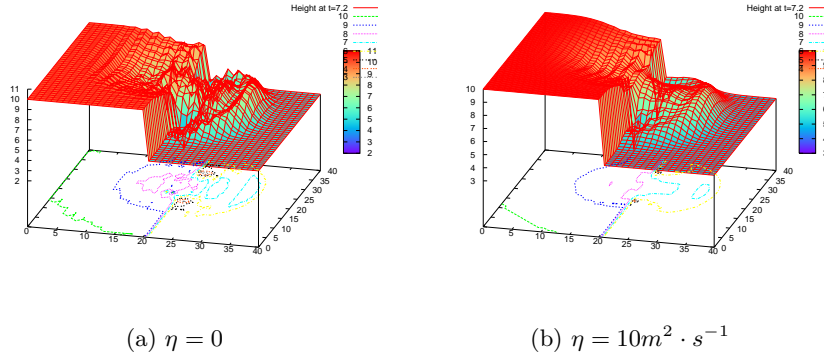
Here,  $u_{\nu, \mu}(t)$  denotes the discrete solution at the grid point  $(x_\nu, y_\nu, t)$ ,  $\mathbf{d}_{\nu, \mu} := \mathbf{d}(\mathbf{u}_{\nu, \mu})$ , and  $\mathbf{v} := U_{\mathbf{u}} = [gh - \frac{1}{2}(u^2 + v^2), u, v]^\top$  is the entropy variable. Numerical flux  $\mathbf{f}^*$  and  $\mathbf{g}^*$  are constructed separately along two different phase paths dictated by two sets of vectors  $\{\ell^{x^j}\}$  and  $\{\ell^{y^j}\}$ .  $\{h^j\}$  and  $\{u^j\}$  are intermediate values of height and velocity along the path. The above difference scheme (18a)-(18c) is an entropy stable scheme with no artificial viscosity in the sense that the following discrete entropy balance is satisfied,



$$\begin{aligned} \frac{d}{dt} \sum_{\nu, \mu} U(\mathbf{u}_{\nu, \mu}(t)) \Delta x \Delta y = & -\eta \sum_{\nu, \mu} \left\{ \widehat{h_{\nu+\frac{1}{2}, \mu}} \left[ \left( \frac{\Delta \mathbf{u}_{\nu+\frac{1}{2}, \mu}}{\Delta x} \right)^2 + \left( \frac{\Delta \mathbf{v}_{\nu+\frac{1}{2}, \mu}}{\Delta x} \right)^2 \right] \right. \\ & \left. + \widehat{h_{\nu, \mu+\frac{1}{2}}} \left[ \left( \frac{\Delta \mathbf{u}_{\nu, \mu+\frac{1}{2}}}{\Delta y} \right)^2 + \left( \frac{\Delta \mathbf{v}_{\nu, \mu+\frac{1}{2}}}{\Delta y} \right)^2 \right] \right\} \Delta x \Delta y. \quad (19) \end{aligned}$$

(19) is a discrete analogue of the entropy balance statement (17).

Equipped by RK3, we test the entropy stable scheme (18a)-(18c) by the 2D partial Dam-Break problem with free-slip boundary described in [FC1990]. Both the inviscid and viscous case are tested. The water surface profiles at time  $t = 7.2s$  are recorded in **Fig.2**.



**Fig. 3.** Shallow water equations, Dam-Break,  $200 \times 200 m^2$  basin, free-slip boundary,  $\Delta x = \Delta y = 5 m$ ,  $\Delta t = 5 \times 10^{-3} s$

Comparing 3(b) to 3(a), we observe the improvements in smoothness of the numerical solutions. There is no analytical reference solution for this test case, but other numerical results are available in [FC1990].

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