# On Lipschitz inversion of nonlinear redundant representations

Radu Balan and Dongmian Zou

ABSTRACT. In this note we show that reconstruction from magnitudes of frame coefficients (the so called "phase retrieval problem") can be performed using Lipschitz continuous maps. Specifically we show that when the nonlinear analysis map  $\alpha : H \to \mathbb{R}^m$  is injective, with  $(\alpha(x))_k = |\langle x, f_k \rangle|^2$ , where  $\{f_1, \dots, f_m\}$  is a frame for the Hilbert space H, then there exists a left inverse map  $\omega : \mathbb{R}^m \to H$  that is Lipschitz continuous. Additionally we obtain that the Lipschitz constant of this inverse map is at most 12 divided by the lower Lipschitz constant of  $\alpha$ .

# 1. Introduction

Let H be an n-dimensional Hilbert space and  $\mathcal{F} = \{f_1, f_2, \dots, f_m\}$  be a spanning set for H. Since H has finite dimension,  $\mathcal{F}$  forms a frame for H, that is, there exist two positive constants A and B such that

(1.1) 
$$A \|x\|^{2} \leq \sum_{k=1}^{m} |\langle x, f_{k} \rangle|^{2} \leq B \|x\|^{2}, \quad \forall x \in H$$

In this paper, H can be a real or complex Hilbert space and the result applies to both cases. On H we consider the equivalent replation  $x \sim y$  if and only if there is a scalar a of magnitude one, |a| = 1, so that y = ax. Let  $\hat{H} = H/\sim$  denote the set of equivalence classes. Note that  $\hat{H} \setminus \{0\}$  is equivalent to the cross-product between a real or complex projective space  $\mathcal{P}^{n-1}$  of dimension n-1 and the positive semiaxis  $\mathbb{R}^+ = (0, \infty)$ .

Let  $\alpha$  denote the nonlinear map

(1.2) 
$$\alpha: H \to \mathbb{R}^m , \ \alpha(x) = \left( |\langle x, f_k \rangle|^2 \right)_{1 \le k \le m}$$

Note that  $\alpha$  induces a nonlinear map which is well defined on  $\hat{H}$ . By abuse of notation we also denote it by  $\alpha$ . The *phase retrieval problem* (or the *phaseless reconstruction problem*) refers to analyzing when  $\alpha$  is an injective map, and in this

<sup>2010</sup> Mathematics Subject Classification. Primary 15A29, 65H10, 90C26.

Key words and phrases. Frames, Lipschitz maps, stability.

The first author was supported in part by NSF Grant DMS-1109498 and DMS-1413249. He also acknowledges fruitful discussions with Krzysztof Nowak and Hugo Woerdeman (both from Drexel University) who pointed out several references, with Stanislav Minsker (Duke University) for pointing out [**ZB**], and Vern Paulsen (University of Houston), Marcin Bownick (University of Oregon) and Friedrich Philipp (Technical University of Berlin).

case to finding "good" left inverses. The frame  $\mathcal{F}$  is said to be *phase retrievable* if the nonlinear map  $\alpha$  is injective. In this paper we assume  $\alpha$  is injective (hence  $\mathcal{F}$  is phase retrievable).

A continuous map  $f : (X, d_X) \to (Y, d_Y)$ , defined between metric spaces X and Y with distances  $d_X$  and  $d_Y$  respectively, is said to be Lipschitz continuous with Lipschitz constant Lip(f) if

(1.3) 
$$Lip(f) := \sup_{x_1 \neq x_2 \in X} \frac{d_Y(f(x_1), f(x_2))}{d_X(x_1, x_2)} < \infty$$

Existing literature (e.g.  $[\mathbf{BW}]$ ) establishes that when  $\alpha$  is injective, it is also bi-Lipschitz for metric  $d_1$  (the nuclear norm, which is defined in (2.4)) in  $\hat{H}$  and Euclidian norm in  $\mathbb{R}^m$ . As a consequence of these results we obtain that a left inverse of  $\alpha$  is Lipschitz when restricted to the image of  $\hat{H}$  through  $\alpha$ . In this paper we show that this left inverse admits a Lipschitz continuous extension to the entire  $\mathbb{R}^m$ . Surprisingly we obtain the Lipschitz constant of this extension is just a small factor larger than the minimal Lipschitz constant, a factor that is independent of the dimension n or the number of frame vectors m.

The Lipschitz properties of  $\alpha$  is related to the stability of reconstruction. Consider the noisy model for the reconstruction of a signal x with the measurements

(1.4) 
$$y = \alpha(x) + \nu$$

where  $\nu \in \mathbb{R}^m$  is the noise. The stability of specific reconstruction methods is studied in, for instance, **[BCMN]**, **[BH]** and **[CSV]**. In general, if we can find (guaranteed by the result of this paper) a Lipschitz continuous map defined on the whole  $\mathbb{R}^m$ , say  $\omega : (\mathbb{R}^m, \|\cdot\|) \to (\hat{H}, d_1)$ , such that  $\omega(\alpha(x)) = x$  for all  $x \in \hat{H}$ , then we have a stable reconstruction in the following sense: Let  $x_0 \in \hat{H}$  be the original signal and  $y_1$  be the measurement from the noisy model (1.4) with noise  $\nu_1$ . Let  $x_1 = \omega(y_1)$ . Then

(1.5) 
$$d_1(x_0, x_1) = d_1(\omega(\alpha(x_0)), \omega(y_1)) \le Lip(\omega) \cdot ||\alpha(x_0) - y_1|| = Lip(\omega) \cdot ||\nu_1||$$

Moreover, let  $y_1$  and  $y_2$  be two different measurements of  $\alpha(x_0)$  from (1.4) with noise  $\nu_1$ ,  $\nu_2$ , respectively. Then we have

(1.6) 
$$d_1(x_1, x_2) = d_1(\omega(y_1), \omega(y_2)) \le Lip(\omega) \cdot ||y_1 - y_2|| = Lip(\omega) \cdot ||\nu_1 - \nu_2||.$$

Note that in general (1.5) does not imply (1.6).

#### 2. Notations and Statement of Main Results

The nonlinear map  $\alpha$  defined by (1.2) naturally induces a linear map between the space  $Sym(H) = \{T : H \to H, T = T^*\}$  of symmetric operators on H and  $\mathbb{R}^m$ :

(2.1) 
$$\mathcal{A}: Sym(H) \to \mathbb{R}^m , \ \mathcal{A}(T) = (\langle Tf_k, f_k \rangle)_{1 \le k \le m}$$

Note that  $\alpha(x) = \mathcal{A}(\llbracket x, x \rrbracket)$  where

(2.2) 
$$\llbracket x, y \rrbracket = \frac{1}{2} (\langle \cdot, x \rangle y + \langle \cdot, y \rangle x)$$

denotes the symmetric outer product between vectors x and y.

The linear map  $\mathcal{A}$  has first been observed in [**BBCE**] and it has been exploited successfully in various papers e.g. [**Ba2**, **CSV**, **Ba3**].

Let  $S^{p,q}(H)$  denote the set of symmetric operators that have at most p strictly positive eigenvalues and q strictly negative eigenvalues.

In particular  $S^{1,0}(H)$  denotes the set of non-negative symmetric operators of rank at most one:

$$(2.3) \qquad S^{1,0}(H) = \{T \in Sym(H) \ s.t. \ \exists x \in H, \forall y \in H \ , \ T(y) = \langle y, x \rangle x\}$$

In [**Ba4**] we studied in more depth geometric and analytic properties of this set. The map  $\alpha$  is injective if and only if  $\mathcal{A}$  restricted to  $S^{1,0}(H)$  is injective. On the space  $\hat{H}$  we define the *matrix norm induced metrics* as follows: For every  $1 \leq p \leq \infty$  and  $x, y \in H$ ,

(2.4) 
$$d_p(\hat{x}, \hat{y}) = \| [\![x, x]\!] - [\![y, y]\!] \|_p = \begin{cases} \left( \sum_{k=1}^n (\sigma_k)^p \right)^{1/p} & for \quad 1 \le p < \infty \\ \max_{1 \le k \le n} \sigma_k & for \quad p = \infty \end{cases}$$

where  $(\sigma_k)_{1 \le k \le n}$  are the singular values of the matrix  $[\![x, x]\!] - [\![y, y]\!]$ , which is of rank at most 2. In particular, for p = 1,  $d_1$  corresponds to the nuclear norm  $\|\cdot\|_1$  in Sym(H) (the sum of singular values); for  $p = \infty$ ,  $d_\infty$  corresponds to the operator norm  $\|\cdot\|_{\infty}$  in Sym(H) (the largest singular value). In the following parts, when no subscript is used,  $\|\cdot\| = \|\cdot\|_2$ .

In previous papers [Ba4, BW] we showed a result that is equivalent to the following theorem:

THEOREM 2.1. If  $\mathcal{F}$  is phase retrievable, then there exist constants  $a_0$ ,  $b_0 > 0$  such that for every  $x, y \in H$ ,

(2.5) 
$$\sqrt{a_0}d_1(x,y) \le \|\alpha(x) - \alpha(y)\| \le \sqrt{b_0}d_1(x,y)$$

*i.e.*  $\alpha$  is bi-Lipschitz between  $(\hat{H}, d_1)$  and  $(\mathbb{R}^m, \|\cdot\|)$ .

Consequently, the inverse map defined on the range of  $\alpha$  from metric space  $(\alpha(\hat{H}), \|\cdot\|)$  to  $(\hat{H}, d_1)$ :

(2.6) 
$$\tilde{\omega}: \alpha(\hat{H}) \subset \mathbb{R}^m \to \hat{H}, \ \tilde{\omega}(c) = x \text{ if } \alpha(x) = c$$

is Lipschitz and its Lipschitz constant is bounded by  $\frac{1}{\sqrt{a_0}}$ .

Now we state the main result of this paper:

THEOREM 2.2. Let  $\mathcal{F} = \{f_1, \dots, f_m\}$  be a phase retrievable frame for the ndimensional Hilbert space H, and let  $\alpha : \hat{H} \to \mathbb{R}^m$  denote the injective nonlinear analysis map  $\alpha(x) = (|\langle x, f_k \rangle|^2)_{1 \le k \le m}$ . Then there exists a Lipschitz continuous function  $\omega : \mathbb{R}^m \to \hat{H}$  such that  $\omega(\alpha(x)) = x$  for all  $x \in \hat{H}$ .  $\omega$  has a Lipschitz constant Lip( $\omega$ ) between  $(\mathbb{R}^m, \|\cdot\|_2)$  and  $(\hat{H}, d_1)$  bounded by

(2.7) 
$$Lip(\omega) \le \frac{12}{\sqrt{a_0}}$$

The proof of Theorem 2.2, presented in the next section, requires construction of a special Lipschitz map. We believe this particular result is interesting in itself and may be used in other constructions. Due to its importance we state it here:

LEMMA 2.3. Consider the spectral decomposition of any self-adjoint operator in Sym(H),  $A = \sum_{k=1}^{d} \lambda_{m(k)} P_k$ , where  $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_n$  are the *n* eigenvalues including multiplicities, and  $P_1, \ldots, P_d$  are the orthogonal projections associated to

the d distinct eigenvalues. Additionally, m(1) = 1 and m(k+1) = m(k) + r(k), where  $r(k) = rank(P_k)$  is the multiplicity of eigenvalue  $\lambda_{m(k)}$ . Then the map

(2.8) 
$$\pi: Sym(H) \to S^{1,0}(H) , \ \pi(A) = (\lambda_1 - \lambda_2)P_1$$

satisfies the following two properties:

- (1)  $\pi$  is Lipschitz continuous from  $(Sym(H), \|\cdot\|_{\infty})$  to  $(S^{1,0}(H), \|\cdot\|_{\infty})$  with Lipschitz constant less than or equal to 6;
- (2)  $\pi(A) = A$  for all  $A \in S^{1,0}(H)$ .

The estimates of Theorem 2.2 and Lemma 2.3 are not optimal. In a separate publication [**BZ**] we improve it and extend the estimates to other metrics.

# 3. Proof of Results

The proof of Theorem 2.2 requires the Kirszbraun Theorem (see, e.g. [**WW**], Ch.10-11). Kirszbraun Theorem applies when two metric spaces have the following property:

DEFINITION 3.1 (Kirszbraun Property (K)). Let X and Y be two metric spaces with metric  $d_x$  and  $d_y$  respectively. (X, Y) is said to have Property (K) if for any pair of families of closed balls  $\{B(x_i, r_i) : i \in I\}, \{B(y_i, r_i) : i \in I\}$ , such that  $d_y(y_i, y_j) \leq d_x(x_i, x_j)$  for each  $i, j \in I$ , it holds that  $\bigcap_{i \in I} B(x_i, r_i) \neq \emptyset \Rightarrow$  $\bigcap_{i \in I} B(y_i, r_i) \neq \emptyset$ .

Kirszbraun Theorem states the following:

THEOREM 3.2 (Kirszbraun Theorem). Let X and Y be two metric spaces and (X, Y) has Property (K). Suppose U is a subset of X and  $f: U \to Y$  is a Lipschitz map. Then there exists a Lipschitz map  $F: X \to Y$  which extends f to X and Lip(F) = Lip(f). In particular, (X, Y) has Property (K) if X and Y are Hilbert spaces and  $d_X$ ,  $d_Y$  are the correspondingly induced metrics.

Note that we cannot use the Kirszbraun Theorem directly to extend  $\tilde{\omega}$ . Specifically, our pair of spaces  $(\mathbb{R}^m, \hat{H})$  does not satisfy the Kirszbraun Property. We give the following counterexample.

EXAMPLE 3.3. Let  $X = \mathbb{R}^m$  for any  $m \in \mathbb{N}$  and  $Y = \hat{H}$  with  $H = \mathbb{C}^2$ . We want to show that (X, Y) does not have Property (K). Let  $\tilde{y}_1 = (1, 0)$  and  $\tilde{y}_2 = (0, \sqrt{3})$ be representitives of  $y_1, y_2 \in Y$ , respectively. Then  $d_1(y_1, y_2) = 4$ . Pick any two points  $x_1, x_2$  in X with  $||x_1 - x_2|| = 4$ . Then  $B(x_1, 2)$  and  $B(x_2, 2)$  intersect at  $x_3 = (x_1 + x_2)/2 \in X$ . It suffices to show that the closed balls  $B(y_1, 2)$  and  $B(y_2, 2)$ have no intersection in H. Assume on the contrary that the two balls intersect at  $y_3$ , then pick a representive of  $y_3$ , say  $\tilde{y}_3 = (a, b)$  where  $a, b \in \mathbb{C}$ . It can be computed that

(3.1) 
$$d_1(y_1, y_3) = |a|^4 + |b|^4 - 2|a|^2 + 2|b|^2 + 2|a|^2|b|^2 + 1$$

and

(3.2) 
$$d_1(y_2, y_3) = |a|^4 + |b|^4 + 6|a|^2 - 6|b|^2 + 2|a|^2|b|^2 + 9$$

Set  $d_1(y_1, y_3) = d_1(y_2, y_3) = 2$ . Take the difference of the right hand side of (3.1) and (3.2), we have  $|b|^2 - |a|^2 = 1$  and thus  $|b|^2 \ge 1$ . However, the right hand side of (3.1) can be rewritten as  $(|a|^2 + |b|^2 - 1)^2 + 4|b|^2$ , so  $d_1(y_1, y_3) = 2$  would imply that  $|b|^2 \le 1/2$ . This is a contradiction.

We start with the proof of Lemma 2.3.

PROOF OF LEMMA 2.3. We prove (1) only. (2) follows directly from the expression of  $\pi$ .

Let  $A, B \in Sym(H)$  where  $A = \sum_{k=1}^{d} \lambda_{m(k)} P_k$  is the spectral decomposition as stated in the lemma and  $B = \sum_{k'=1}^{d'} \mu_{m(k')} Q_{k'}$  is a decomposition in the same manner. We now show that

(3.3) 
$$\|\pi(A) - \pi(B)\|_{\infty} \le 6 \|A - B\|_{\infty}$$

Assume  $\lambda_1 - \lambda_2 \leq \mu_1 - \mu_2$ . Otherwise switch the notations for A and B. If  $\mu_1 - \mu_2 = 0$  then  $\pi(A) = \pi(B) = 0$  and the inequality (3.3) is satisfied. Assume now  $\mu_1 - \mu_2 > 0$ . Thus  $Q_1$  is of rank 1 and therefore  $||Q_1||_{\infty} = 1$ .

First note thats

(3.4) 
$$\pi(A) - \pi(B) = (\lambda_1 - \lambda_2)P_1 - (\mu_1 - \mu_2)Q_1 \\ = (\lambda_1 - \lambda_2)(P_1 - Q_1) + (\lambda_1 - \mu_1 - (\lambda_2 - \mu_2))Q_1$$

Here  $||P_1||_{\infty} = ||Q_1||_{\infty} = 1$ . Therefore we have  $||P_1 - Q_1||_{\infty} \le 1$  since  $P_1, Q_1$ are both positive semidefinite.

Also, by Weyl's inequality (see [**Bh**] III.2) we have  $|\lambda_i - \mu_i| \leq ||A - B||_{\infty}$  for each *i*. Apply this to i = 1, 2 we get  $|\lambda_1 - \mu_1 - (\lambda_2 - \mu_2)| \leq |\lambda_1 - \mu_1| + |\lambda_2 - \mu_2| \leq |\lambda_1 - \mu_2| \leq |\lambda_1 - \mu_1| + |\lambda_2 - \mu_2| \leq |\lambda_1 - \mu_1| + |\lambda_2 - \mu_2| \leq |\lambda_1 - \mu_2| \leq |\lambda_1 - \mu_1| + |\lambda_2 - \mu_2| \leq |\lambda_1 - \mu_2| \leq |\lambda_2 - \mu_2| \leq |\lambda_2 - \mu_2| + |\lambda_2 - \mu_2| + |\lambda_2 - \mu_2| \leq |\lambda_2 - \mu_2| + |\lambda_2 - \mu_2| \leq |\lambda_2 - \mu_2| + |\lambda_2 - \mu_2$  $2 \|A - B\|_{\infty}.$  Thus  $|\lambda_1 - \mu_1| + |\lambda_2 - \mu_2| \le 2 \|A - B\|_{\infty}.$ Let  $g := \lambda_1 - \lambda_2, \ \delta := \|A - B\|_{\infty},$  then apply the above inequality to (3.4) we

get

(3.5) 
$$\|\pi(A) - \pi(B)\|_{\infty} \le g \|P_1 - Q_1\|_{\infty} + 2\delta \le g + 2\delta$$

If  $0 \le g \le 4\delta$ , then  $\|\pi(A) - \pi(B)\|_{\infty} \le 6\delta$  and we are done. Now we consider the case where  $g > 4\delta$ . In the complex plane, let  $\gamma = \gamma(t)$  be the (directed) circle centered at  $\lambda_1$  with radius g/2. Since  $\delta < g/4$  we have  $|\lambda_1 - \mu_1| < g/4$  and  $|\lambda_2 - \mu_2| < g/4$ . Therefore the contour encloses  $\mu_1$  but not  $\mu_2$ .



Using holomorphic calculus, we can put

$$(3.6) P_1 = -\frac{1}{2\pi i} \oint_{\gamma} R_A dz$$

and

$$(3.7) Q_1 = -\frac{1}{2\pi i} \oint_{\gamma} R_B dz$$

where  $R_A = (A - zI)^{-1}$  and  $R_B = (B - zI)^{-1}$ . Now we have

(3.8)  
$$P_{1} - Q_{1} = \frac{1}{2\pi i} \oint_{\gamma} (R_{B} - R_{A}) dz$$
$$= \frac{1}{2\pi i} \oint_{\gamma} R_{A} (B - A) R_{B} dz$$

Thus

$$||P_1 - Q_1||_{\infty} \leq \frac{1}{2\pi} \cdot 2\pi \cdot \frac{g}{2} \cdot \max_z ||A - zI||_{\infty} ||B - A||_{\infty} ||B - zI||_{\infty}$$

$$= \frac{g\delta}{2} \cdot \max_z \max\left\{\frac{1}{|\lambda_1 - z|}, \frac{1}{|\lambda_2 - z|}\right\} \cdot \max_z \left\{\frac{1}{|\mu_1 - z|}, \frac{1}{|\mu_2 - z|}\right\}$$

$$= \frac{g\delta}{2} \cdot \frac{2}{g} \cdot \frac{4}{g}$$

$$= \frac{4\delta}{g}$$

Thus by the first inequality in (3.5) we have

(3.10) 
$$\|\pi(A) - \pi(B)\|_{\infty} \le 4\delta + 2\delta = 6\delta$$

Therefore, we have proved (3.3).

REMARK 3.4. Using the integration contour from  $[\mathbf{ZB}]$ , one can derive a slightly stronger bound. We plan to present this result in  $[\mathbf{BZ}]$ .

REMARK 3.5. Numerical experiments seem to suggest that the optimal Lipschitz constant in Lemma 2.3 is 2.

Now we are ready to prove Theorem 2.2.

PROOF OF THEOREM 2.2. We construct a Lipschitz map  $\omega : (\mathbb{R}^m, \|\cdot\|) \to (\hat{H}, d_1)$  such that  $\omega(\alpha(x)) = x$  for all  $x \in \hat{H}$  and  $Lip(\omega) \leq \frac{12}{\sqrt{a_0}}$ .

Let  $M = \alpha(\hat{H}) \subset \mathbb{R}^m$ . By hypothesis, there is a map  $\tilde{\omega}_1 : M \to \hat{H}$  that is Lipschitz continuous and satisfies  $\tilde{\omega}_1(\alpha(x)) = x$  for all  $x \in \hat{H}$ . Additionally, the Lipschitz bound between  $(M, \|\cdot\|)$  (that is, M with Euclidian distance) and  $(\hat{H}, d_1)$ is given by  $1/\sqrt{a_0}$ .

First we change the metric on  $\hat{H}$  from  $d_1$  to  $d_2$  and embed isometrically  $\hat{H}$  into Sym(H) with Frobenius norm (i.e. Euclidian metric):

$$(3.11) \qquad (M, \|\cdot\|) \xrightarrow{\tilde{\omega}_1} (\hat{H}, d_1) \xrightarrow{i_{1,2}} (\hat{H}, d_2) \xrightarrow{\kappa} (Sym(H), \|\cdot\|_{Fr})$$

where  $i_{1,2}(x) = x$  is the identity of  $\hat{H}$  and  $\kappa$  is the isometry given by

(3.12)  $\kappa : \hat{H} \to S^{1,0}(H), \quad x \mapsto \llbracket x, x \rrbracket$ 

## This is a free offprint provided to the author by the publisher. Copyright restrictions may apply.

20

Obviously we have  $Lip(i_{1,2}) = 1$  and  $Lip(\kappa) = 1$ . Thus we obtain a map  $\tilde{\omega}_2 : (M, \|\cdot\|) \to (Sym(H), \|\cdot\|_{Fr})$  of Lipschitz constant

(3.13) 
$$Lip(\tilde{\omega}_2) \le Lip(\tilde{\omega}_1)Lip(i_{1,2})Lip(\kappa) = \frac{1}{\sqrt{a_0}}$$

Kirszbraun Theorem (Theorem 3.2) extends isometrically  $\tilde{\omega}_2$  from M to the entire  $\mathbb{R}^m$  with Euclidian metric  $\|\cdot\|$ . Thus we obtain a Lipschitz map  $\omega_2 : (\mathbb{R}^m, \|\cdot\|) \to (Sym(H), \|\cdot\|_{F_r})$  of Lipschitz constant  $Lip(\omega_2) = Lip(\tilde{\omega}_2) \leq 1/\sqrt{a_0}$  such that  $\omega_2(\alpha(x)) = [x, x]$  for all  $x \in \hat{H}$ .

Now we consider the following maps:

$$(\mathbb{R}^{m}, \|\cdot\|) \xrightarrow{\omega_{2}} (Sym(H), \|\cdot\|_{Fr})$$

$$\xrightarrow{I_{2,\infty}} (Sym(H), \|\cdot\|_{\infty})$$

$$\xrightarrow{\pi} (S^{1,0}(H), \|\cdot\|_{\infty})$$

$$\xrightarrow{\kappa^{-1}} (\hat{H}, d_{\infty})$$

$$\xrightarrow{i_{\infty,1}} (\hat{H}, d_{1})$$

where  $I_{2,\infty}$  and  $i_{\infty,1}$  are identity maps that change the metrics. The map  $\omega$  is defined by

(3.15) 
$$\omega : (\mathbb{R}^m, \|\cdot\|) \to (\hat{H}, d_1), \quad \omega = i_{\infty,1} \cdot \kappa^{-1} \cdot \pi \cdot I_{2,\infty} \cdot \omega_2$$

The Lipschitz constant is bounded by

(3.16)  

$$Lip(\omega) \leq Lip(\omega_2)Lip(I_{2,\infty})Lip(\pi)Lip(\kappa^{-1})Lip(i_{2,1})$$

$$\leq \frac{1}{\sqrt{a_0}} \cdot 1 \cdot 6 \cdot 1 \cdot 2$$

$$= \frac{12}{\sqrt{a_0}}$$

Hence we obtained (2.7).

#### References

- [ABFM] B. Alexeev, A. S. Bandeira, M. Fickus, D. G. Mixon, *Phase Retrieval with Polarization*, SIAM J. Imaging Sci., 7 (1) (2014), 35–66.
- [Ba1] Radu Balan, Equivalence relations and distances between Hilbert frames, Proc. Amer. Math. Soc. 127 (1999), no. 8, 2353–2366, DOI 10.1090/S0002-9939-99-04826-1. MR1600096 (99j:46025)
- [Ba2] R. Balan, On Signal Reconstruction from Its Spectrogram, Proceedings of the CISS Conference, Princeton NJ, May 2010.
- [Ba3] R. Balan, Reconstruction of Signals from Magnitudes of Redundant Representations, available online arXiv:1207.1134v1 [math.FA] 4 July 2012.
- [Ba4] R. Balan, Reconstruction of Signals from Magnitudes of Redundant Representations: The Complex Case, available online arXiv:1304.1839v1 [math.FA] 6 April 2013.
- [BCE1] Radu Balan, Pete Casazza, and Dan Edidin, On signal reconstruction without phase, Appl. Comput. Harmon. Anal. 20 (2006), no. 3, 345–356, DOI 10.1016/j.acha.2005.07.001. MR2224902 (2007b:94054)
- [BCE2] R. Balan, P. Casazza, D. Edidin, Equivalence of Reconstruction from the Absolute Value of the Frame Coefficients to a Sparse Representation Problem, IEEE Signal.Proc.Letters, 14 (5) (2007), 341–343.

- [BBCE] Radu Balan, Bernhard G. Bodmann, Peter G. Casazza, and Dan Edidin, Painless reconstruction from magnitudes of frame coefficients, J. Fourier Anal. Appl. 15 (2009), no. 4, 488–501, DOI 10.1007/s00041-009-9065-1. MR2549940 (2010m:42066)
- [BW] R. Balan and Y. Wang, Invertibility and Robustness of Phaseless Reconstruction, available online arXiv:1308.4718v1. Appl. Comp. Harm. Anal., to appear 2014.
- [BZ] R. Balan and D. Zou, Phase Retrieval using Lipschitz Continuous Maps, available online arXiv:1403.2304v1.
- [BCMN] Afonso S. Bandeira, Jameson Cahill, Dustin G. Mixon, and Aaron A. Nelson, Saving phase: injectivity and stability for phase retrieval, Appl. Comput. Harmon. Anal. 37 (2014), no. 1, 106–125, DOI 10.1016/j.acha.2013.10.002. MR3202304
- [Be] Yoav Benyamini and Joram Lindenstrauss, Geometric nonlinear functional analysis. Vol. 1, American Mathematical Society Colloquium Publications, vol. 48, American Mathematical Society, Providence, RI, 2000. MR1727673 (2001b:46001)
- [Bh] Rajendra Bhatia, Matrix analysis, Graduate Texts in Mathematics, vol. 169, Springer-Verlag, New York, 1997. MR1477662 (98i:15003)
- [BH] B. G. Bodmann and N. Hammen, Stable Phase Retrieval with Low-Redundancy Frames, available online arXiv:1302.5487v1. Adv. Comput. Math., accepted 10 April 2014.
- [CCPW] J. Cahill, P.G. Casazza, J. Peterson, L. Woodland, Phase retrieval by projections, available online arXiv: 1305.6226v3
- [CSV] Emmanuel J. Candès, Thomas Strohmer, and Vladislav Voroninski, PhaseLift: exact and stable signal recovery from magnitude measurements via convex programming, Comm. Pure Appl. Math. 66 (2013), no. 8, 1241–1274, DOI 10.1002/cpa.21432. MR3069958
- [CESV] Emmanuel J. Candès, Yonina C. Eldar, Thomas Strohmer, and Vladislav Voroninski, Phase retrieval via matrix completion, SIAM J. Imaging Sci. 6 (2013), no. 1, 199–225, DOI 10.1137/110848074. MR3032952
- [Ca] Peter G. Casazza, The art of frame theory, Taiwanese J. Math. 4 (2000), no. 2, 129–201. MR1757401 (2001f:42046)
- [Cah] J. Cahill, personal communication, October 2012.
- [FMNW] Matthew Fickus, Dustin G. Mixon, Aaron A. Nelson, and Yang Wang, Phase retrieval from very few measurements, Linear Algebra Appl. 449 (2014), 475–499, DOI 10.1016/j.laa.2014.02.011. MR3191879
- [HG] Matthew J. Hirn and Erwan Y. Le Gruyer, A general theorem of existence of quasi absolutely minimal Lipschitz extensions, Math. Ann. 359 (2014), no. 3-4, 595–628, DOI 10.1007/s00208-013-1003-5. MR3231008
- [Ph] F. Philipp, SPIE 2013 Conference Presentation, August 16, 2013, San Diego, CA.
- [WAM] I. Waldspurger, A. d'Aspremont, S. Mallat, Phase recovery, MaxCut and complex semidefinite programming, Available online: arXiv:1206.0102
- [WW] J. H. Wells and L. R. Williams, Embeddings and extensions in analysis, Springer-Verlag, New York-Heidelberg, 1975. Ergebnisse der Mathematik und ihrer Grenzgebiete, Band 84. MR0461107 (57 #1092)
- [ZB] L. Zwald and G. Blanchard, On the convergence of eigenspaces in kernel Principal Component Analysis, Proc. NIPS 05, vol. 18, 1649-1656, MIT Press, 2006.

DEPARTMENT OF MATHEMATICS AND CENTER FOR SCIENTIFIC COMPUTATION AND MATHEMAT-ICAL MODELING, UNIVERSITY OF MARYLAND, COLLEGE PARK, MARYLAND 20742 *E-mail address:* rvbalan@math.umd.edu

Applied Mathematics and Statistics, and Scientific Computation Program, University of Maryland, College Park, Maryland 20742

E-mail address: zou@math.umd.edu

22