

A Homotopy Method for Predicting the State of Minimal Energy for Chains of Charged Particles

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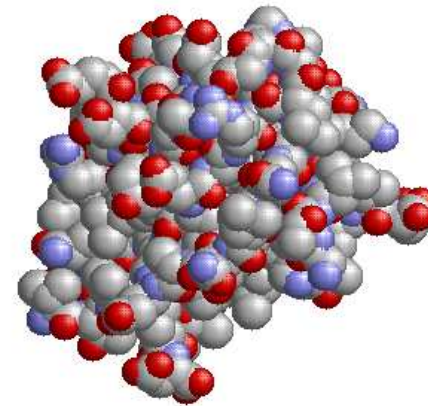
Acknowledgments

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Introduction

- **Protein Folding**

- Sequence of amino acids → three-dimensional structure
- Minimum potential energy assumed for native structure

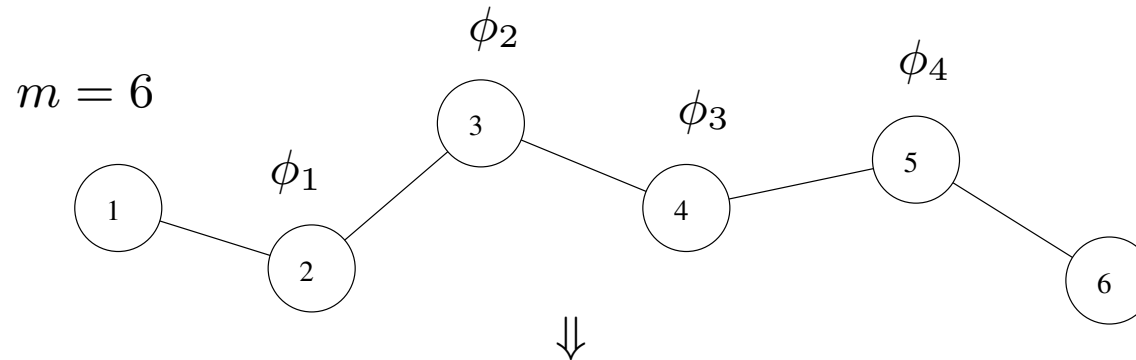


- **Difficult Goal**

- Find structure with minimum potential energy
- Computationally intractable for large proteins

Formulation of the Problem

Chain of m charged particles with charges q_i (2D space)



van der Waals Potential

$$E(\phi) = \sum_{i=1}^{m-2} \sum_{j=i+2}^m \left[\frac{q_i q_j}{R_{ij}(\phi)} + \varepsilon_{ij} \left(\left(\frac{\sigma_{ij}}{R_{ij}(\phi)} \right)^{12} - 2 \left(\frac{\sigma_{ij}}{R_{ij}(\phi)} \right)^6 \right) \right]$$



Optimization Problem

$$\min E(\phi)$$

$$\text{s.t. } 0 \leq \phi_i \leq 2\pi, \quad (i = 1, \dots, m-2)$$

Solving the Optimization Problem

- **Difficulty**

- Many local minima
- Number of minima increases exponentially

- **Classic Approach**

- Gradient methods (*e.g.*, steepest descent)
- Good starting approximation needed
- Converges to *local minimizer*

- **New Approach**

- Homotopy method
- Good starting approximation **not** needed
- Improve likelihood of finding *global minimizer*

General Homotopy Method

Goal: Solve complicated nonlinear system
which may have multiple solutions

$$f(x) = 0, \quad (f : \mathbb{R}^n \rightarrow \mathbb{R}^n).$$

Steps to Solution:

Easy system: $e(x^0) = 0$ (x^0 known)

Homotopy:
$$h(x, \lambda) = \begin{cases} e(x), & \lambda = 0 \\ f(x), & \lambda = 1 \end{cases}$$

e.g., $h(x, \lambda) = \lambda f(x) + (1 - \lambda) e(x)$

Trace Path: Follow $h(x, \lambda) = 0$ from $\lambda = 0$ to $\lambda = 1$

Potential Energy Homotopy

Goal:

$$q^0 = [q_1^0, \dots, q_m^0] \implies E^0(\phi)$$

$$q^* = [q_1^*, \dots, q_m^*] \implies E^*(\phi)$$

$$\begin{array}{ll} \min E^*(\phi) \\ \text{s.t. } 0 \leq \phi \leq 2\pi \end{array} \iff \left\{ \begin{array}{ll} \text{find} & \phi^* \\ \text{s.t.} & \nabla E^*(\phi^*) = 0 \\ & \nabla^2 E^*(\phi^*) > 0 \\ & 0 \leq \phi^* \leq 2\pi \end{array} \right.$$

Homotopy:

$$\begin{aligned} H(\phi, \lambda) &= \nabla \left(\sum_{i=1}^{m-2} \sum_{j=i+2}^m \left[\frac{q_i(\lambda)q_j(\lambda)}{R_{ij}} + \varepsilon_{ij} \left(\left(\frac{\sigma_{ij}}{R_{ij}} \right)^{12} - 2 \left(\frac{\sigma_{ij}}{R_{ij}} \right)^6 \right) \right] \right) \\ &= \begin{cases} \nabla E^0(\phi), & \lambda = 0 \\ \nabla E^*(\phi), & \lambda = 1 \end{cases} \end{aligned}$$

Tracing $H(\phi, \lambda) = 0$

$\phi^0 =$ global minimizer of $E^0(\phi)$

$$\lambda_0 = 0$$

$$k = 0$$

repeat until $\lambda_k = 1$

$$k = k + 1$$

$$\lambda_k = \lambda_{k-1} + (\Delta\lambda)_k$$

$$\phi^k \leftarrow \begin{cases} \text{using } \phi^{k-1} \text{ as initial guess} \\ \text{solve } H(\phi, \lambda_k) = 0 \end{cases}$$

end

$$\phi^* = \phi^k \quad [H(\phi^k, 1) = \nabla E^*(\phi^k) \approx 0]$$

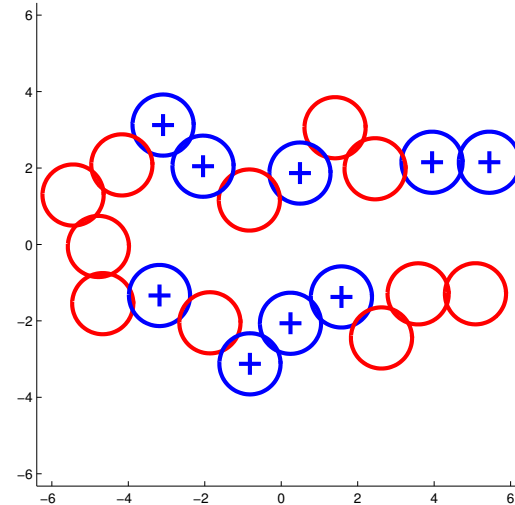
Example 1 – Negligible Difference

$$m = 20$$

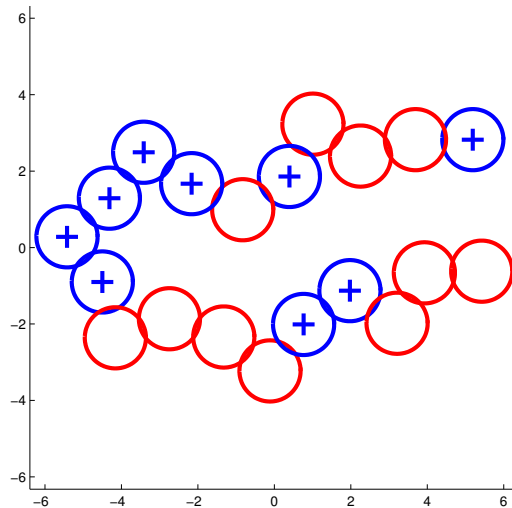
$$q \in \{-1, +1\}$$

$$E^0(\phi) = -22.9708$$

6 changes in q

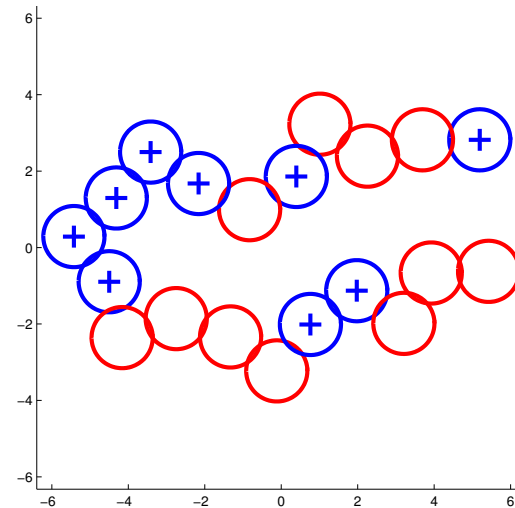


Gradient Method



$$E^*(\phi) = -22.4510$$

Homotopy Method



$$E^*(\phi) = -22.4511$$

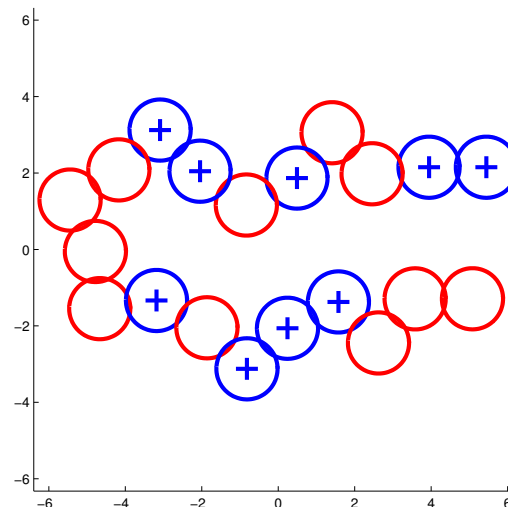
Example 2 – No Difference

$$m = 20$$

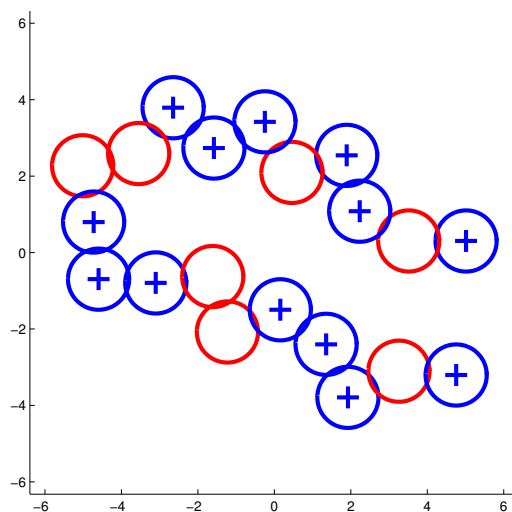
$$q \in \{-1, +1\}$$

$$E^0(\phi) = -22.9708$$

10 changes in q

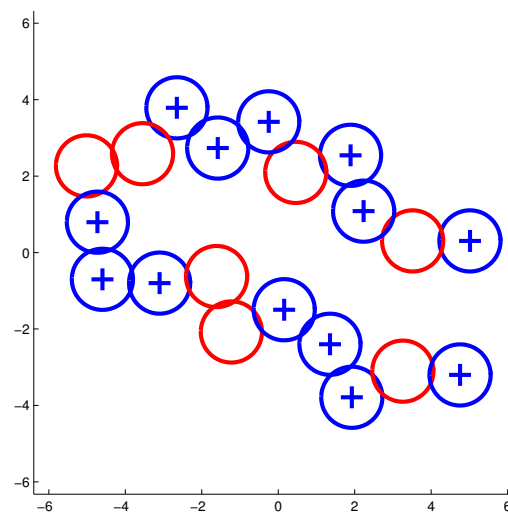


Gradient Method



$$E^*(\phi) = -20.0044$$

Homotopy Method



$$E^*(\phi) = -20.0044$$

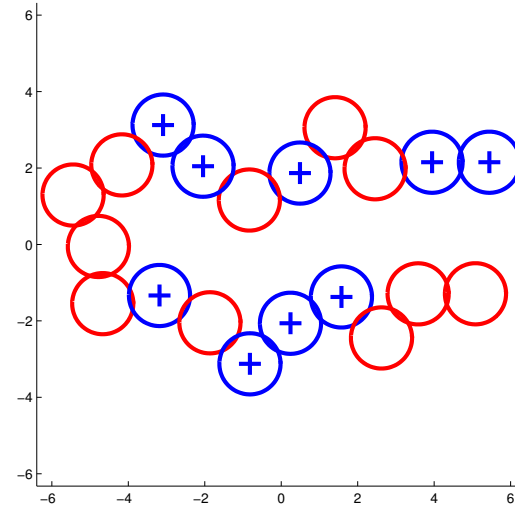
Example 3 - Qualitative Difference

$$m = 20$$

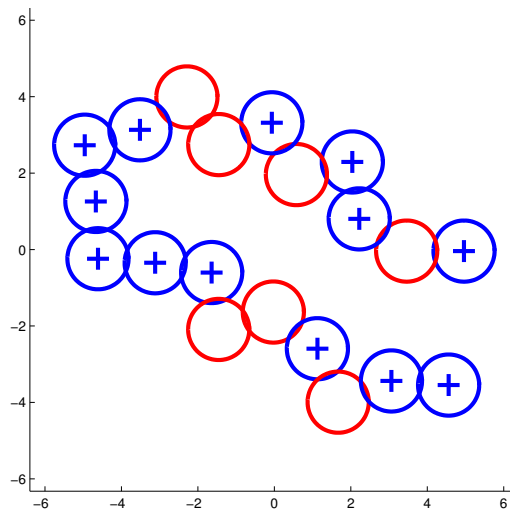
$$q \in \{-1, +1\}$$

$$E^0(\phi) = -22.9708$$

16 changes in q

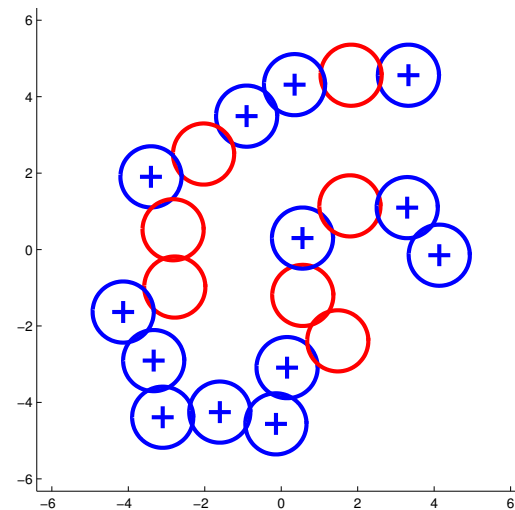


Gradient Method



$$E^*(\phi) = -18.8808$$

Homotopy Method



$$E^*(\phi) = -19.4268$$

Conclusions

- **Homotopy Method**
 - Rivals gradient methods (GM) in accuracy
 - Outperforms GM when many charges change
 - More function evaluations than GM

Future Work

- **Extend ideas to proteins**
- **Software interface for energy models**
 - Models: 2D/3D, Thirumalai/Klimov, AMBER
- **Software interface to Protein Data Bank (PDB)**
 - PDB \rightarrow internal format \rightarrow PDB
- **Homotopy tracing algorithm**
 - Predictor-corrector: ODE + optimization
 - ODE solvers: Euler, Runge-Kutta, etc.
- **Validation of the method**
 - Use existing PDB data